



# Advances in Resistance Welding

How to Maximize Resistance Seam Welding  
Production Speeds and Improve Weld Quality

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**WeldComputer Corporation**

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# How to Make a High Quality Seam

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- Produce fully formed nuggets
- Free of expulsion
- For Gas Tight Requirements: Control spot spacing to make sure each nugget overlaps with the next

# Use Right Machine and Control Setup for the Job

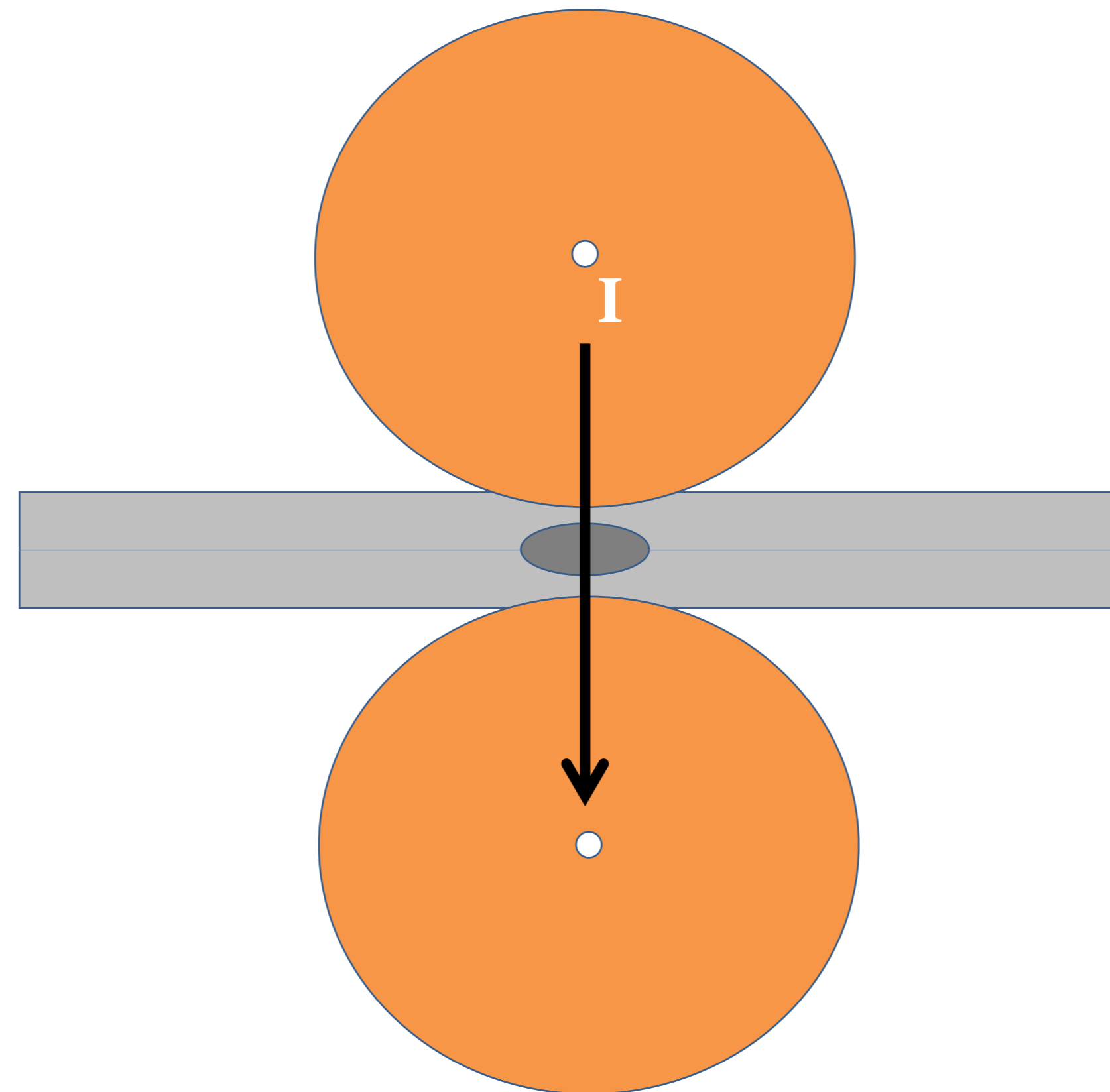
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- Right material electrodes
- Right electrode face diameter
- Apply right electrode force
- Apply the right current function

# Seam Welding

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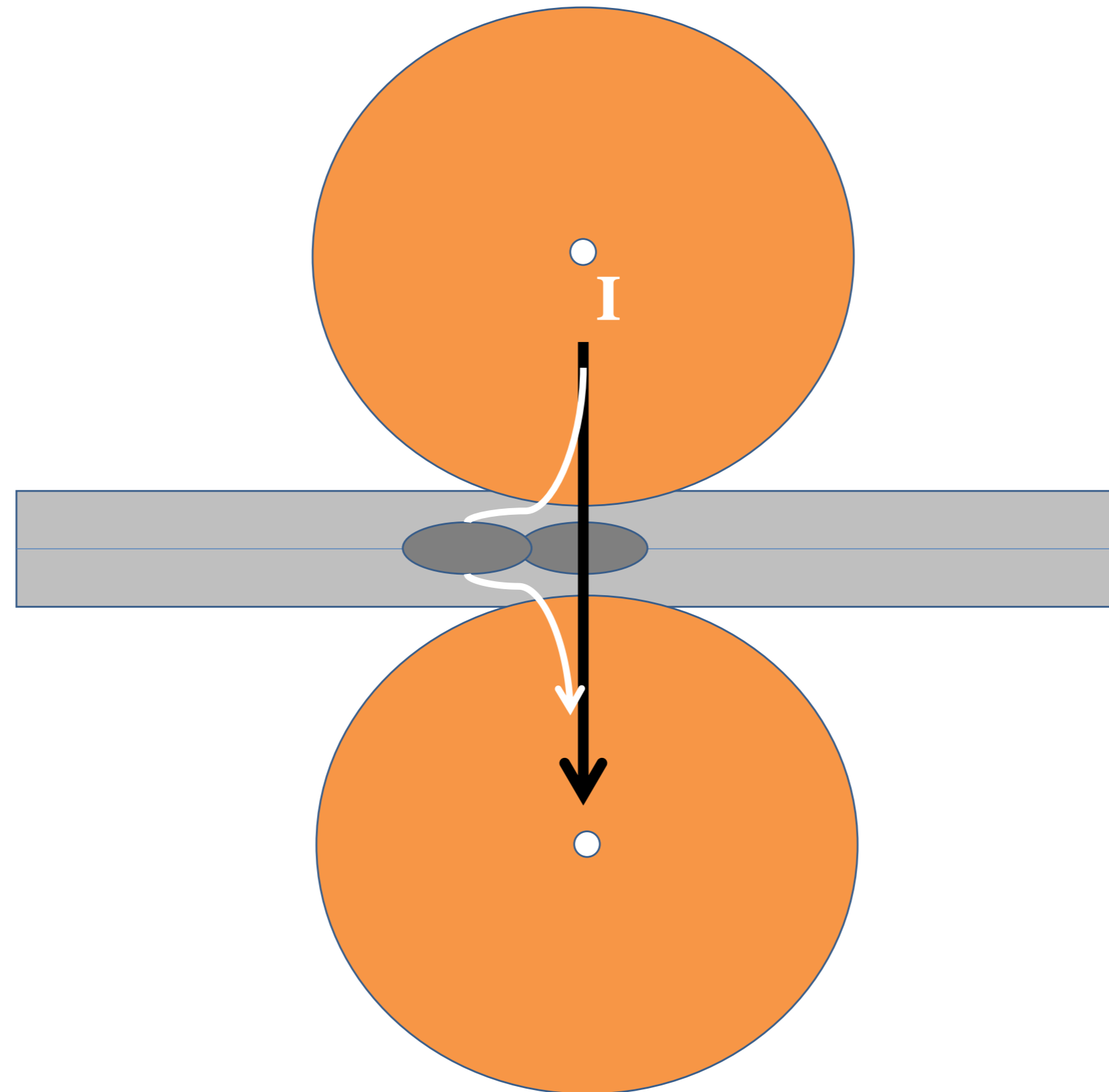
Use right machine, control, electrodes, force & current to make weld.



# Seam Welding

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2nd weld is smaller than 1st because some current shunts through 1st weld.

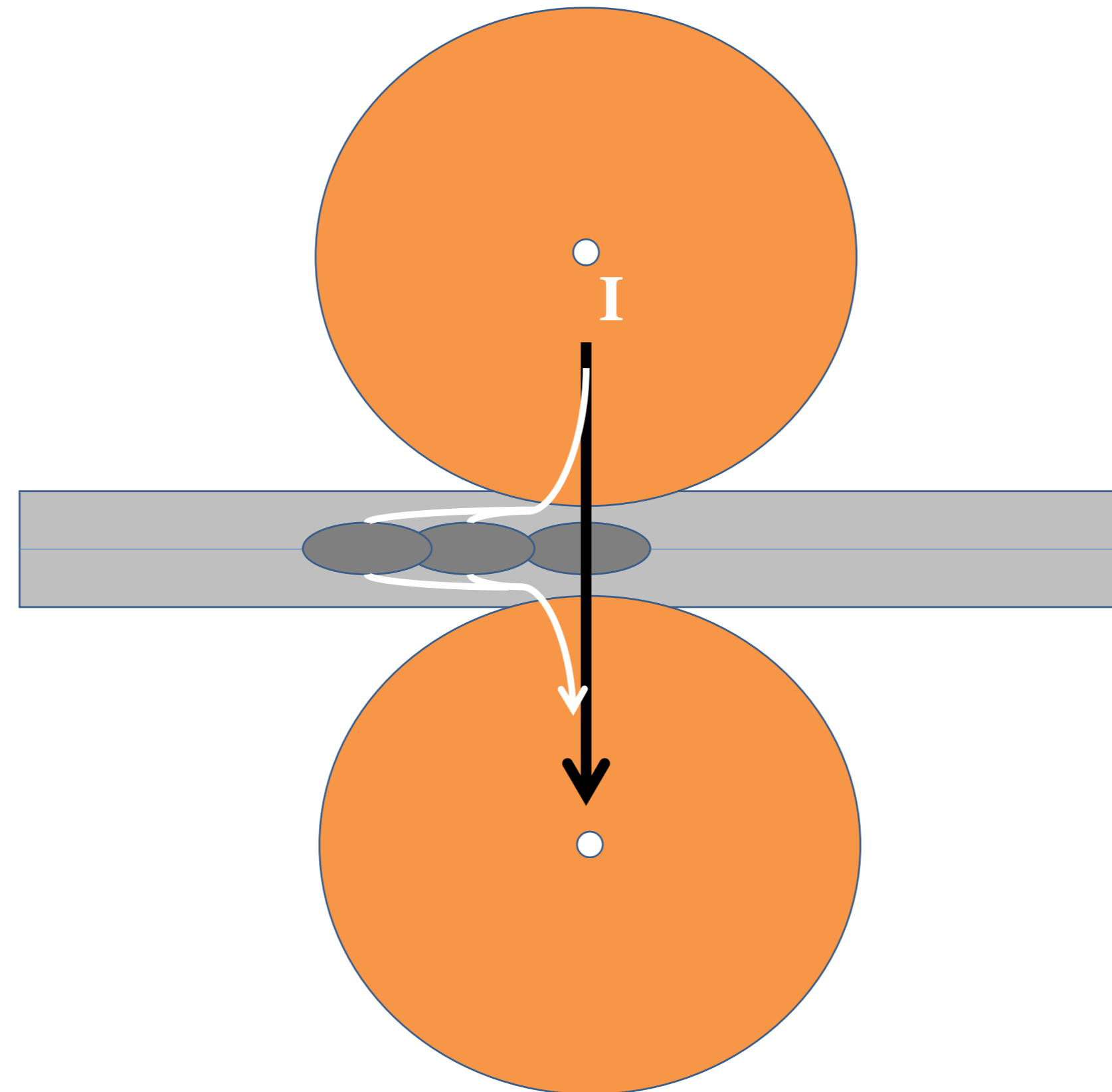




# Seam Welding

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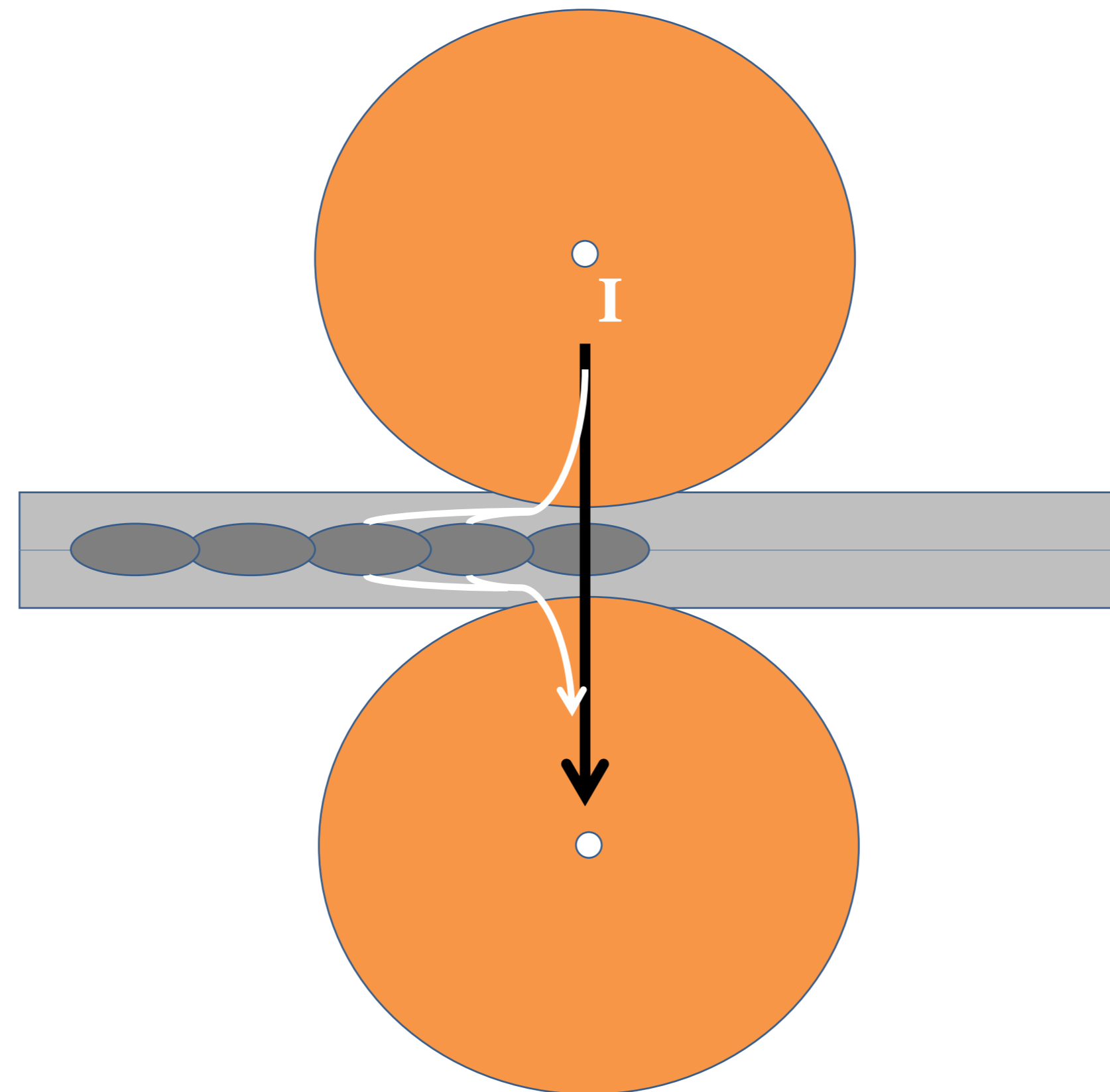
3rd weld is smaller than 2nd because current shunts through 1st & 2nd welds.



# Seam Welding

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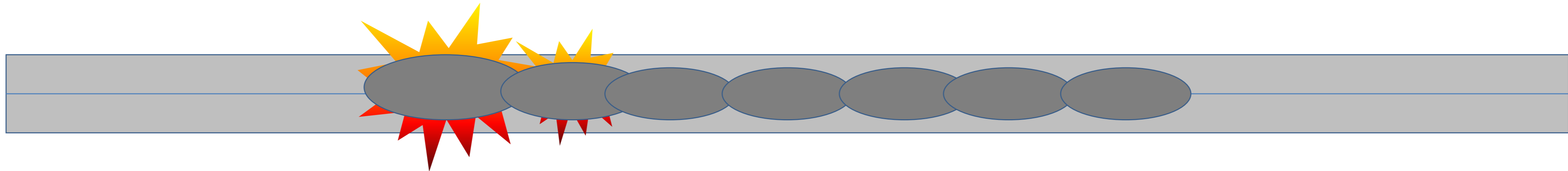
Nugget size stabilizes for remaining welds in seam



# Shunting

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Shunting makes welds hotter at start of seam





# Operations That Make All of These Welds with the Same Current Setting:

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produce smaller nuggets than they really want throughout the entire length of the seam, in order to avoid having the first few welds on the seam be too hot and possibly expulse material,

or...

suffer from having the first few welds be too hot and expulse material, just so the rest of the welds in the seam are the size they want

# Improve Weld Consistency by Managing Shunting at Start of Seam

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- Separate heat setting for 1st spot
- Separate heat setting for 2nd spot
- Separate heat setting for remaining spots in seam

**Problem: Multiple operator adjustments make process too complicated**

# Solution:

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- Provide only a single “current adjustment” for the operator to adjust the main body welding current
- Program the control to automatically scale the heat of the 1st weld and 2nd weld, for the operator, in relation to the main body welding current adjustment that is made
- In a complex process with many parameters of control, this approach is necessary to make the process manageable by the operator

# Intermittent (Roll Spot) Seam Welding

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- Wheels stop to make each weld
- Welding precision is similar to spot welding. Control can take whatever time it needs to make a good weld
- This allows easy use of adaptive control to automatically correct problems like surface contamination and poor part fit-up, instantly cut off heat when expulsion occurs and automatically make a repair weld in place
- Production speed is primarily limited by how fast the wheels can be advanced to the next position and stopped so the next weld can be made

# Continuous Seam Welding

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- Wheels continue rolling while each weld is made
- Control has a fixed time window to make each weld
- No opportunity to vary duration of weld. All adaptive decisions and compensating actions must take place as the weld is being made
- Can achieve much higher production speed than intermittent (roll spot)

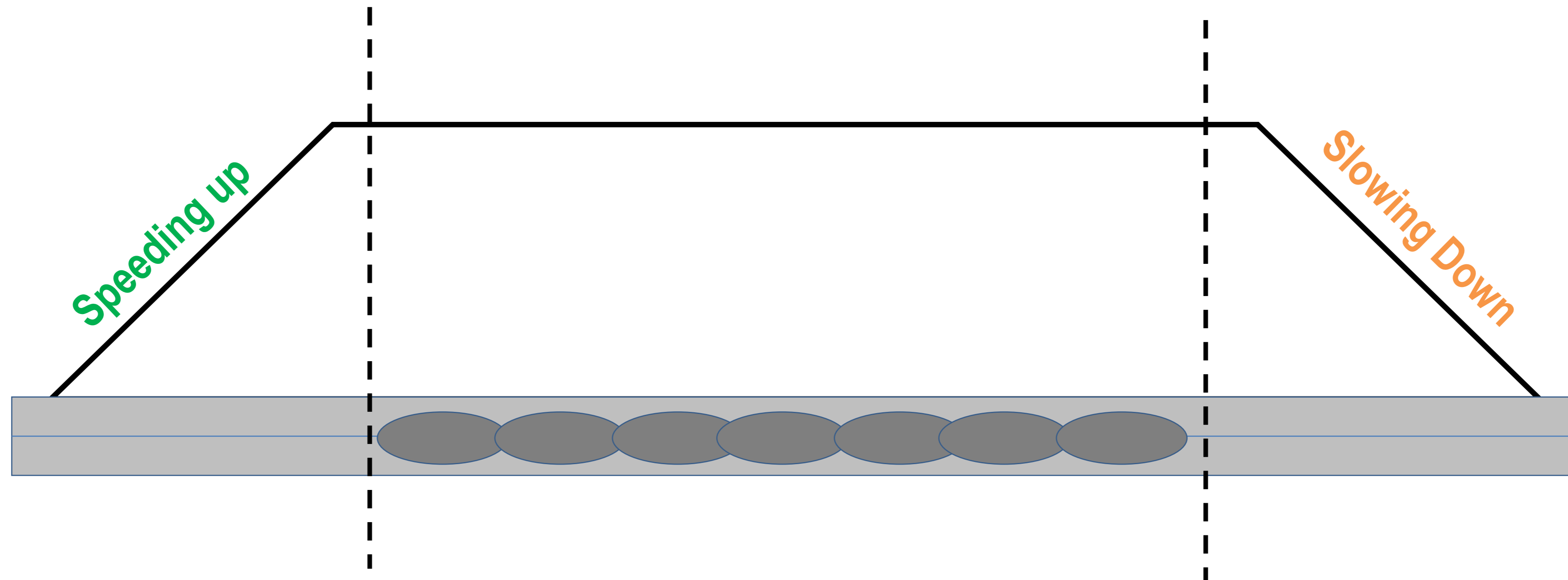
# Three General Arrangements for Continuous Seam Welding

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- Fast: All welds all made at constant wheel travel velocity on the same surface.
- Faster: Welding starts before wheel travel velocity is reached and continues after wheels start slowing down.
- Fastest: Welding occurs edge-to-edge across the entire part.

# Wheel Velocity

All welds occurring at same wheel speed





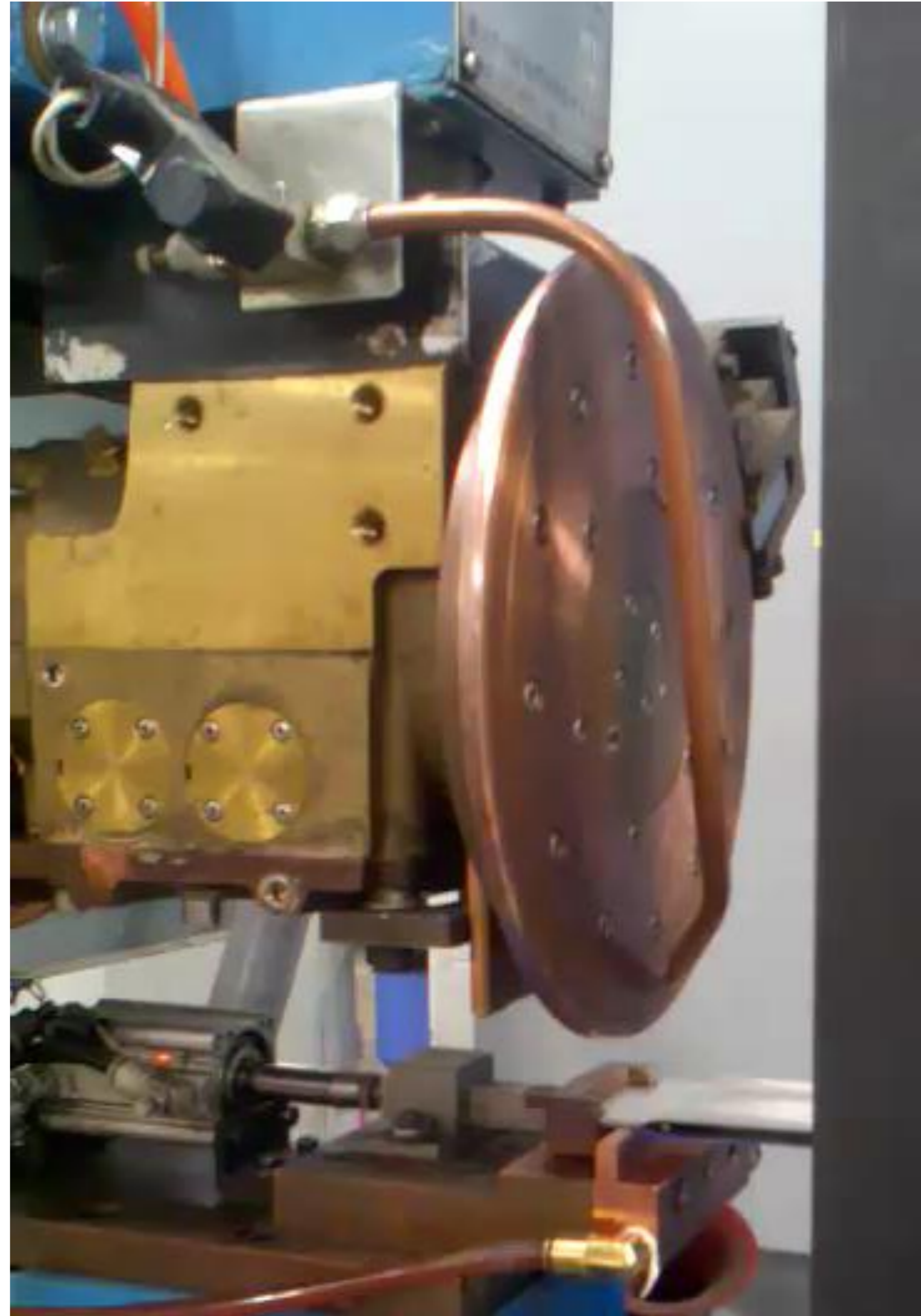
# Manage Shunting at Start of Seam

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- Scale heat down for 2nd spot.
- Scale head down more for 1st spot.

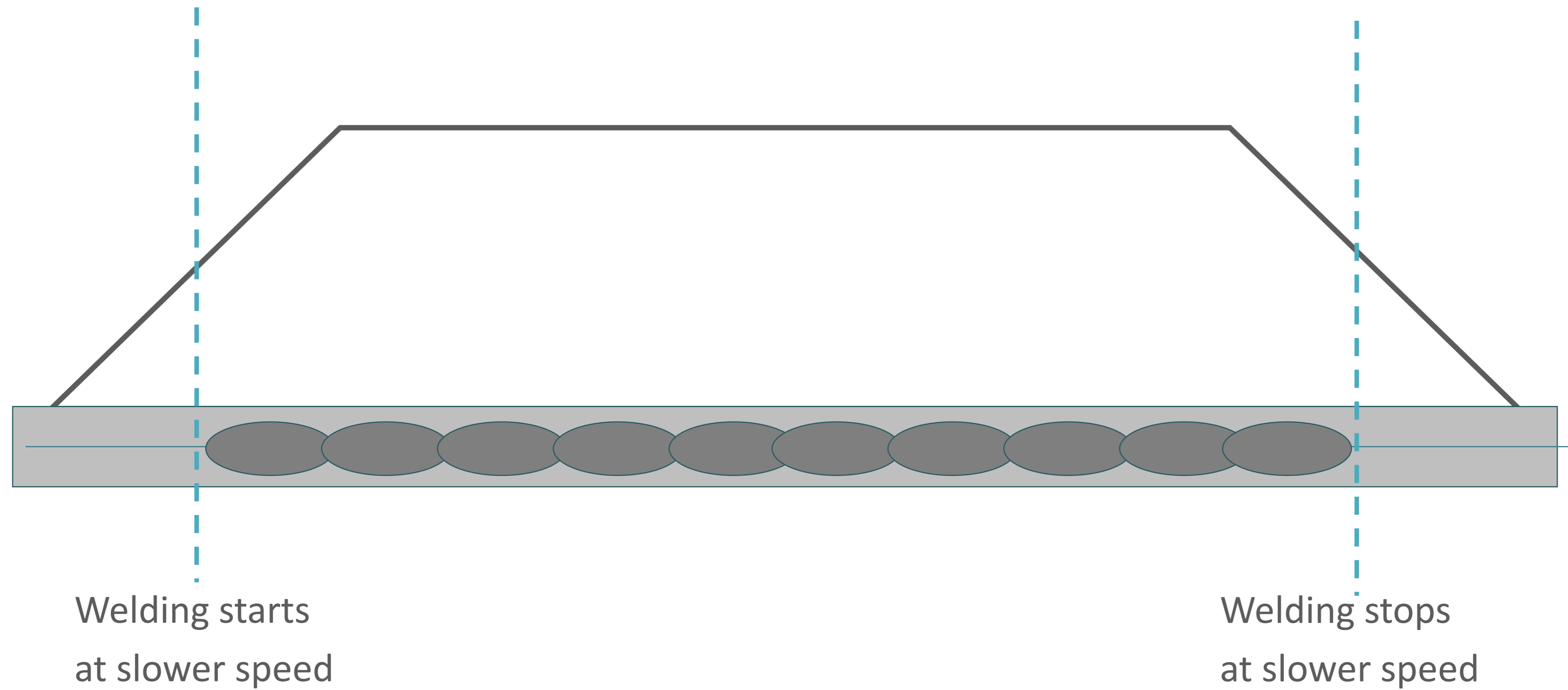


# Seam Welder





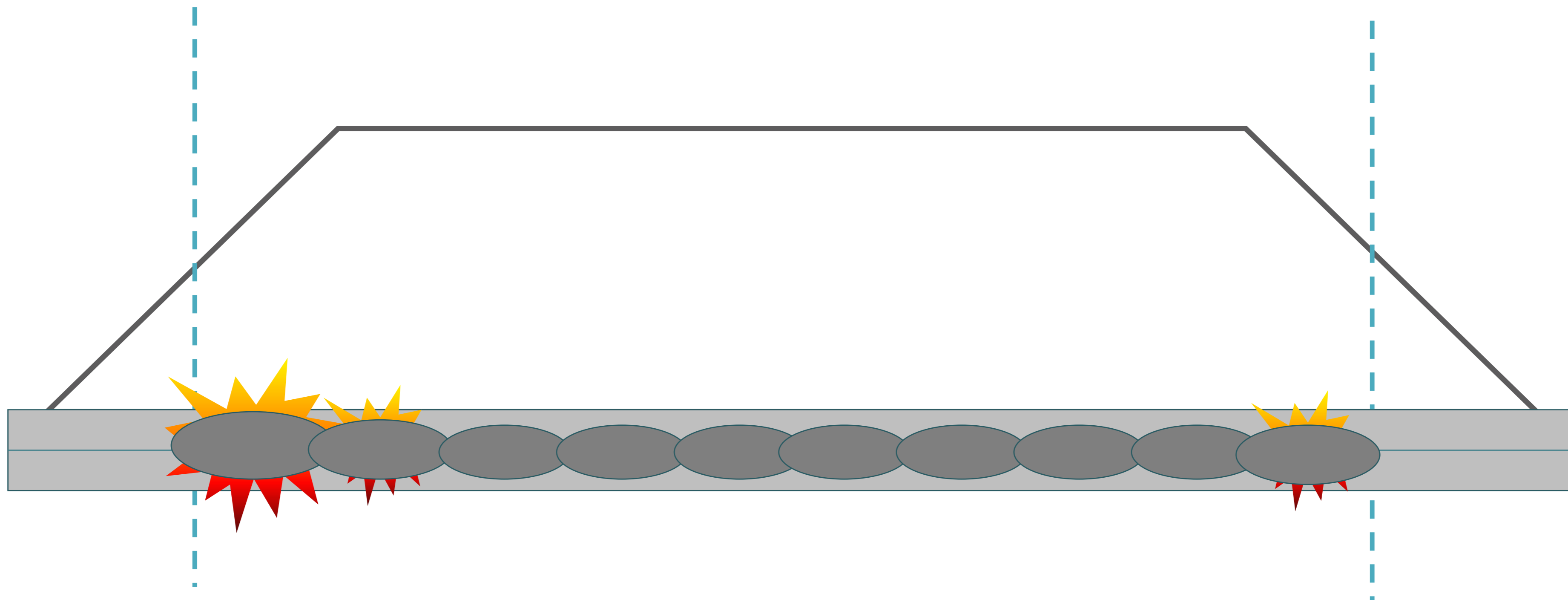
# Wheel Velocity



# Wheel Velocity

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Welding made at slower speeds are hotter



# Continuous Seam Welding

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**Wheel velocity is a major parameter of control, as significant as force and current**

**For a given applied force and current:**

- Lower velocity causes hotter welds
- Higher velocity causes colder welds

# Lower Wheel Velocity Requires Lower Welding Heat

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## **Conventional Solution:**

- Upslope heat at start of seam
- Downslope heat at end of seam

## **Disadvantage:**

Hard to coordinate upslope heat and downslope heat with increasing and decreasing velocity -

Hard to synchronize heat profile with velocity profile

# Lower Wheel Velocity Requires Lower Welding Heat

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## **Adaptive Solution:**

— Program the control to automatically adjust the heat up or down, in relation to instantaneous wheel velocity

## **Advantage:**

Heat: always coordinated & synchronized with wheel velocity

Easy to manage: No operator settings or proximity switches to constantly adjust



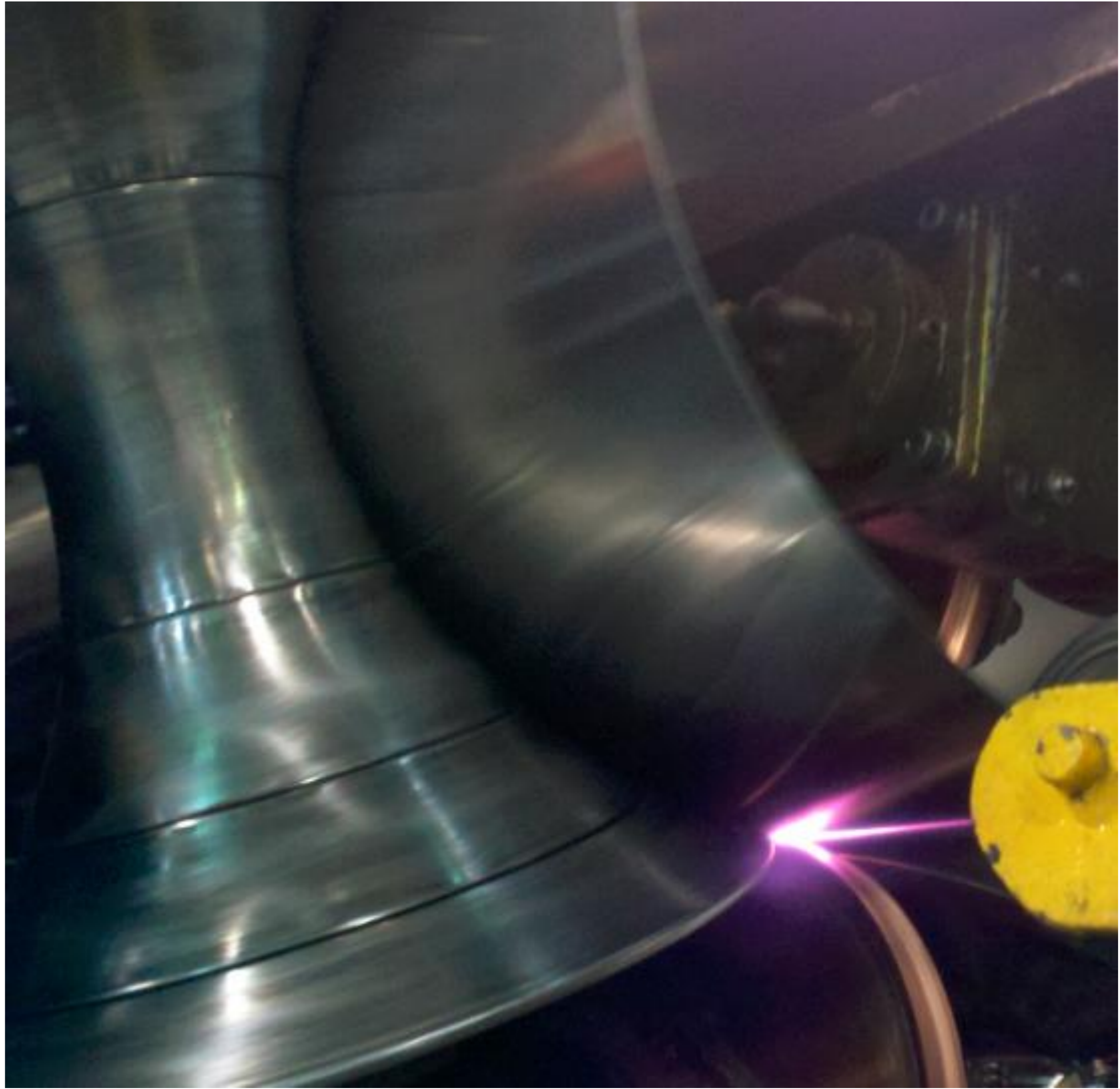
# Examples of Edge to Edge Welding

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- Water heaters
- 55 Gallon drums
- Pails
- Aerosol Cans



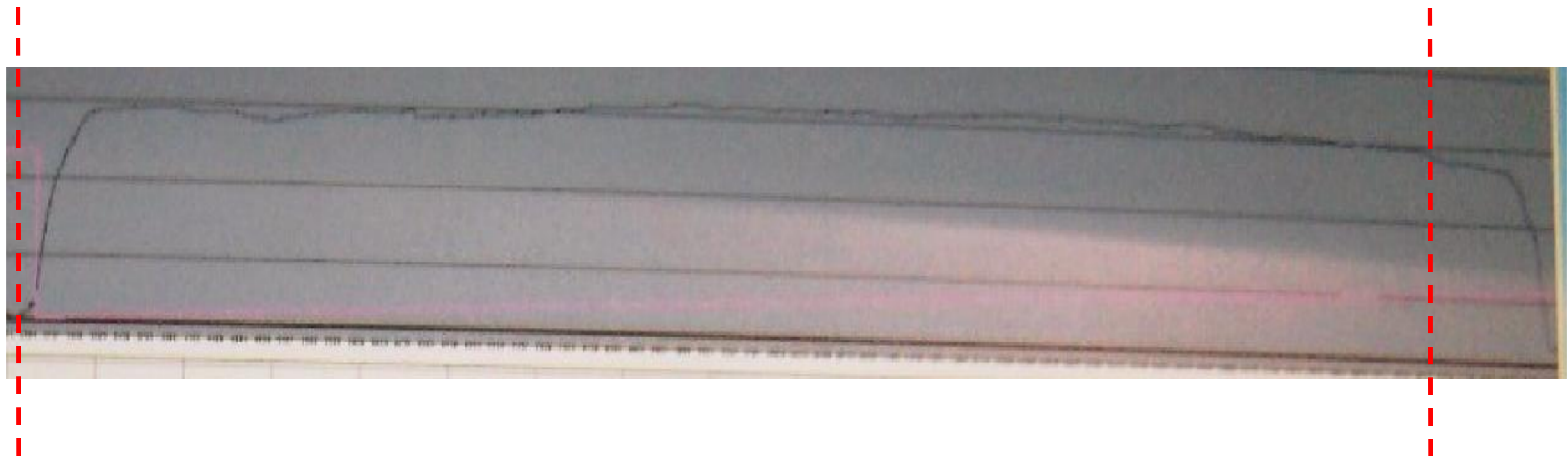
# 55 Gallon Drum Welder





# Typical Wheel Displacement Welding Water Heater with 0.074 Material

Plot of wheel rolling up on front tank, across tank, & off back of tank



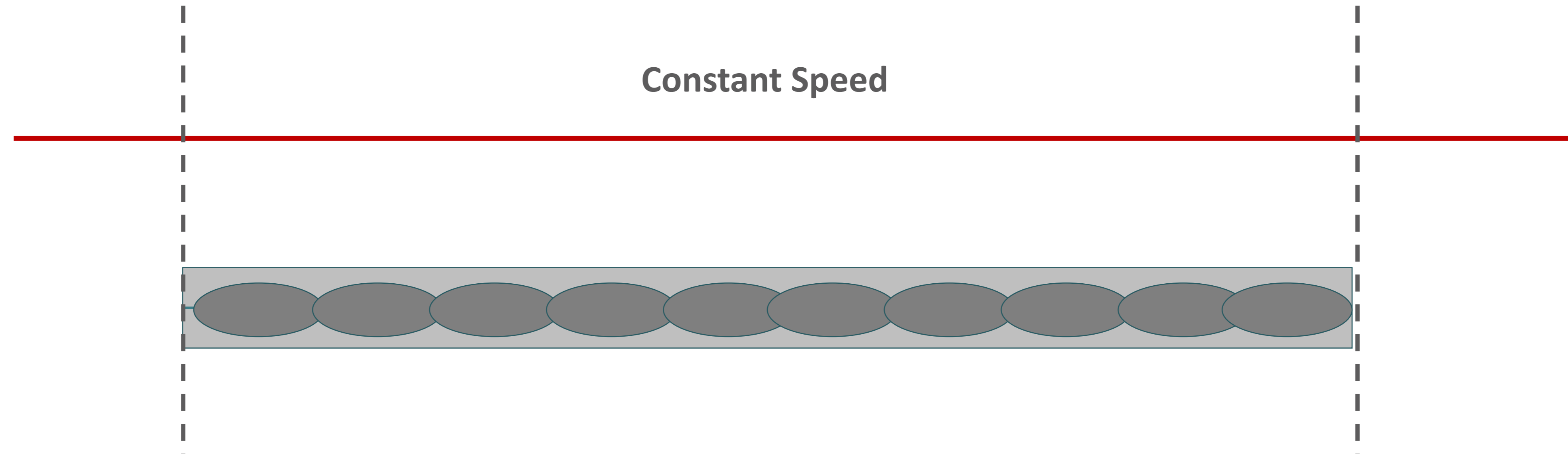
Wheel starts rolling  
up on front of part

Wheel starts rolling  
off back of part

Data collected with WeldComputer<sup>®</sup> Adaptive Control

# Wheel Velocity

Edge to edge adaptive control produces gas tight welds over the entire length of seam



# Typical High Speed Seam Operations Have High Scrap Rates

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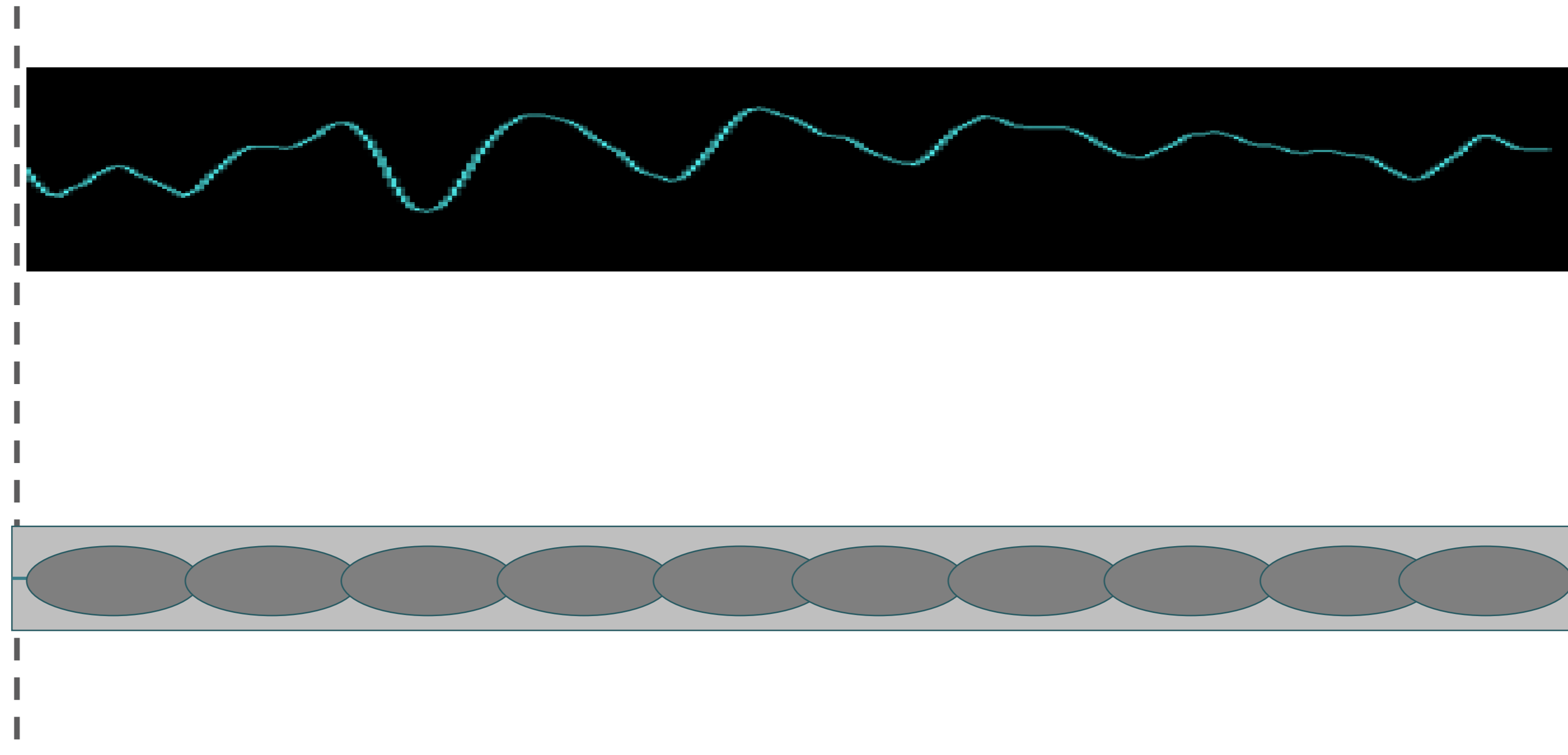
Inability to:

- Control welds on front and back edges
- Prevent hot and cold spots
- Produce consistent current

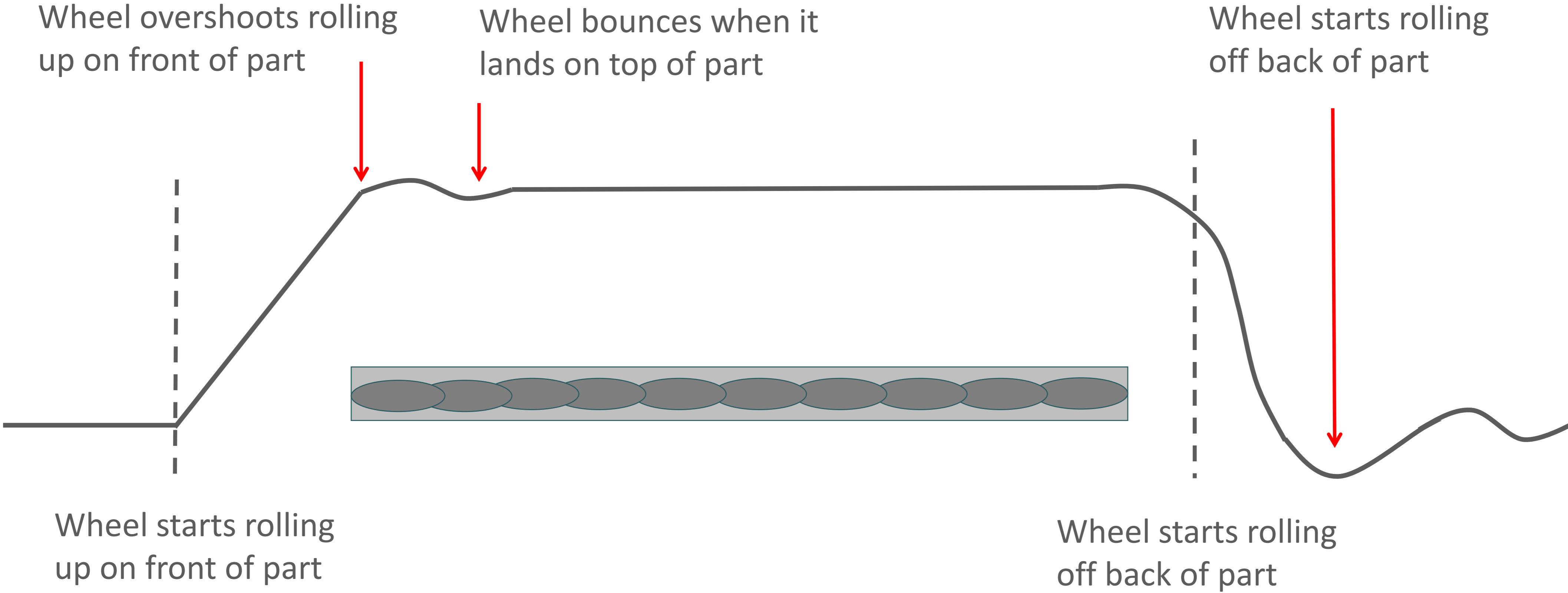
# Wheel Velocity at High Speeds

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Dynamically adjusting weld heat to compensate for velocity fluctuations increases weld consistency and reduces leakers



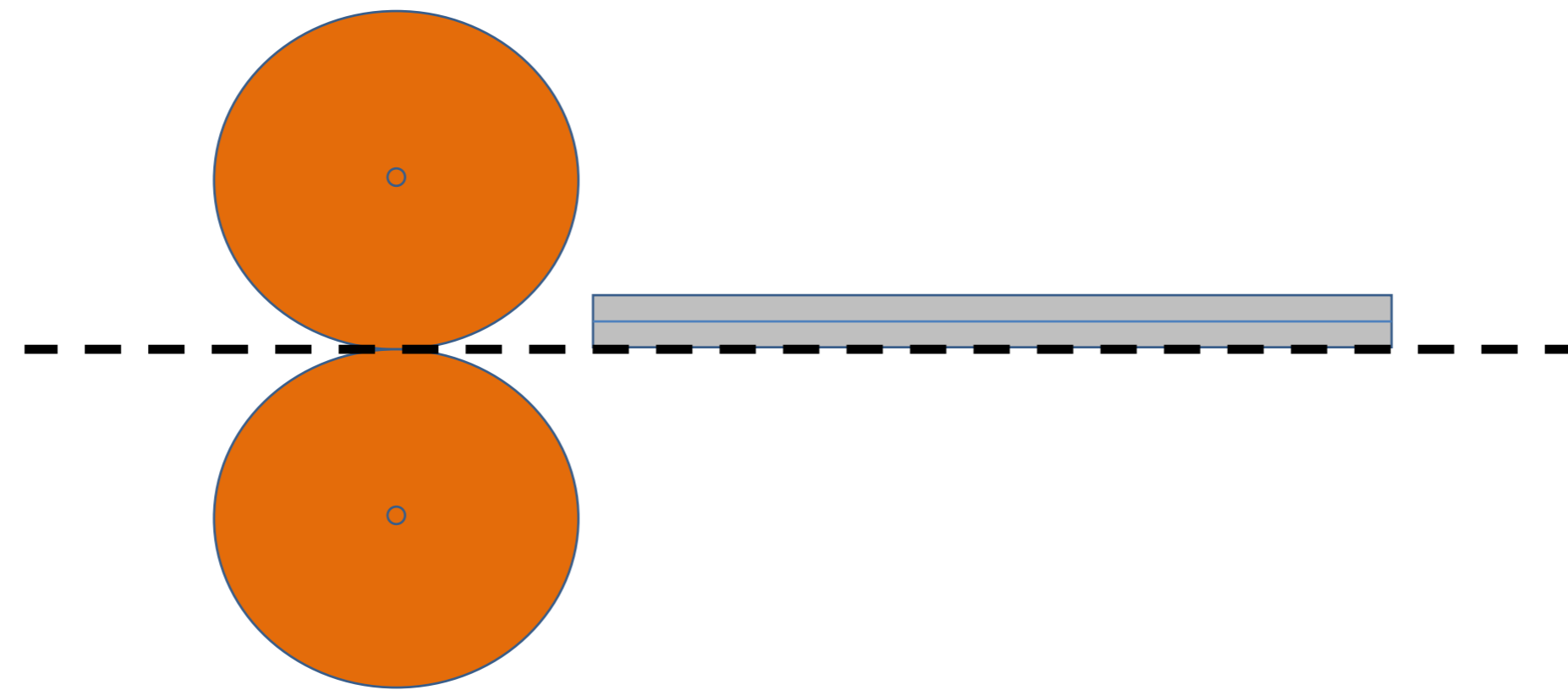
# Wheel Displacement





# Wheel Displacement

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# For edge to edge seam welding at high speeds, conventional heat controls deliver poor performance

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Part proximity sensors used to synchronize heat with front of part entering machine have too much variability to accurately control welding on the front edge

Inability to synchronize heat with back of part leaving machine

Inability to compensate for machine force and velocity variations

SCR based controls have limitations on current wave shape and regulation

Traditional MFDC controls, provide ineffective regulation and heat repeatability, in applications requiring short duration high current pulses



**Adaptive Seam Welding  
Water Heater with  
0.074 material**

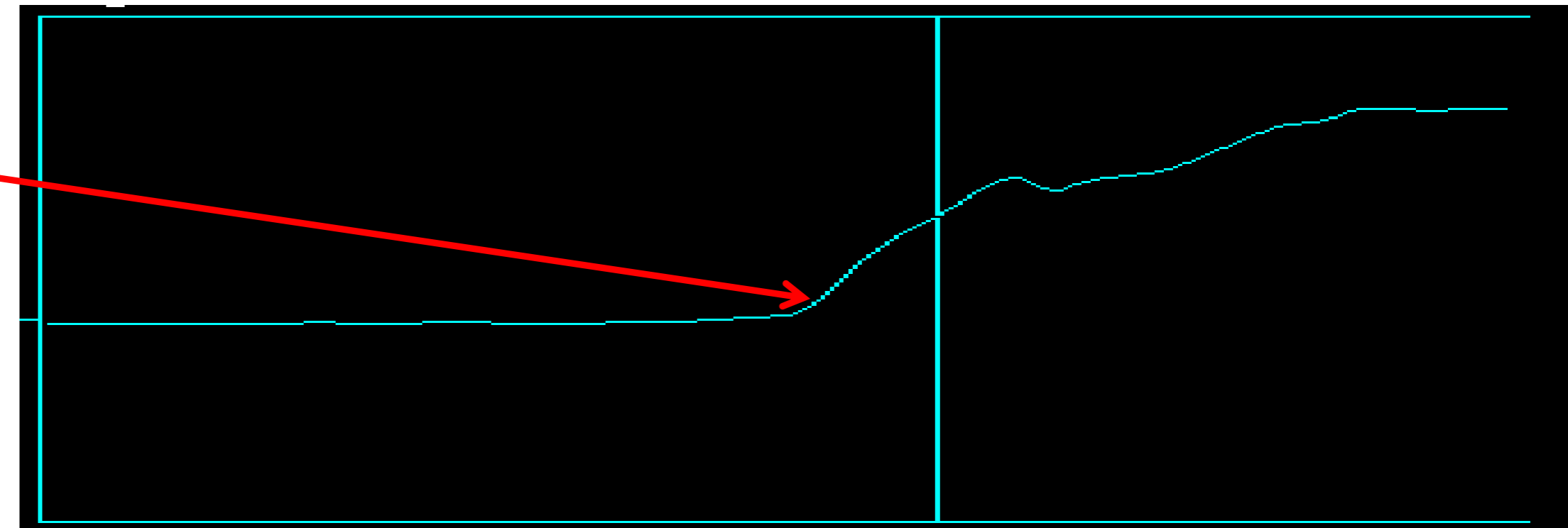




# Current Starting Too Late Makes Undersized Front Edge Weld

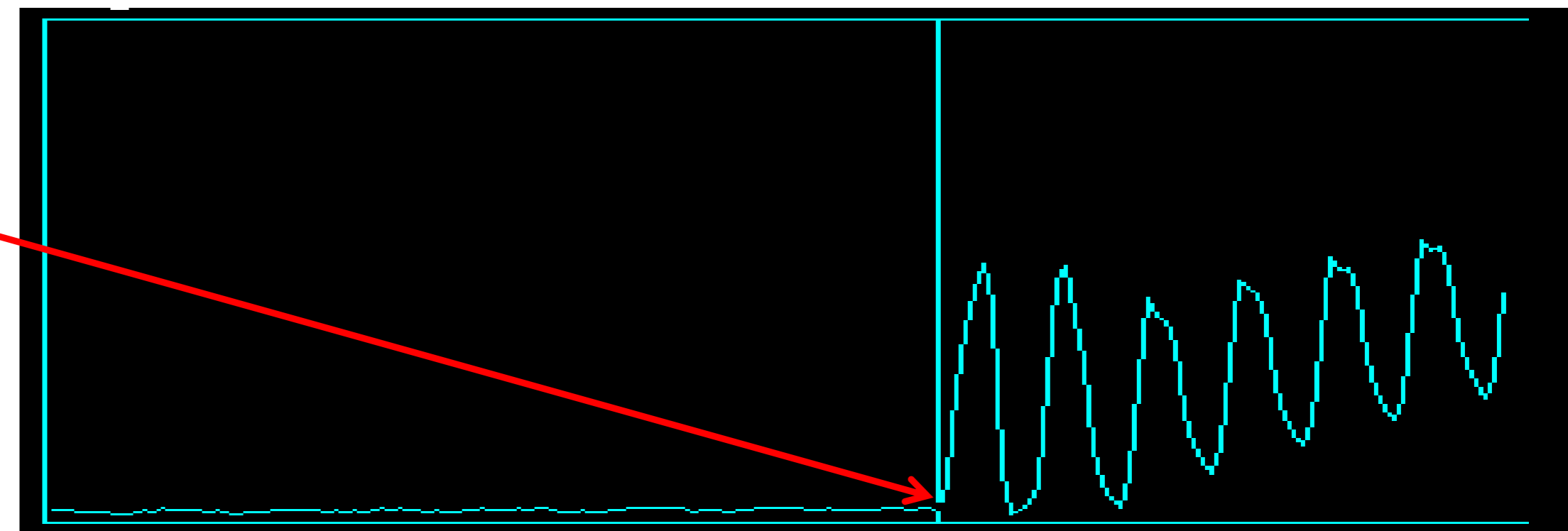
Displacement

Wheel starts rolling up on part here



Current

Current starting here after wheel is already rolling up on part results in undersized weld on front edge



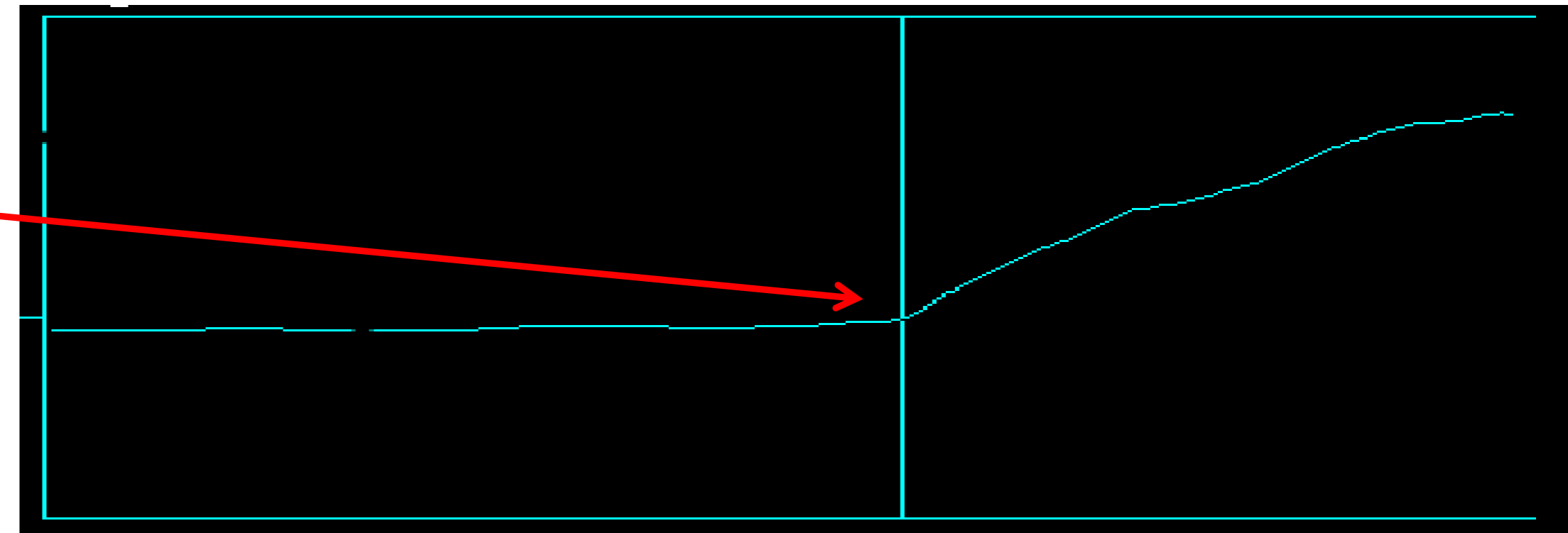
Data collected with WeldView® Monitor

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# Current Starting Too Early Overheats Front Edge of Part

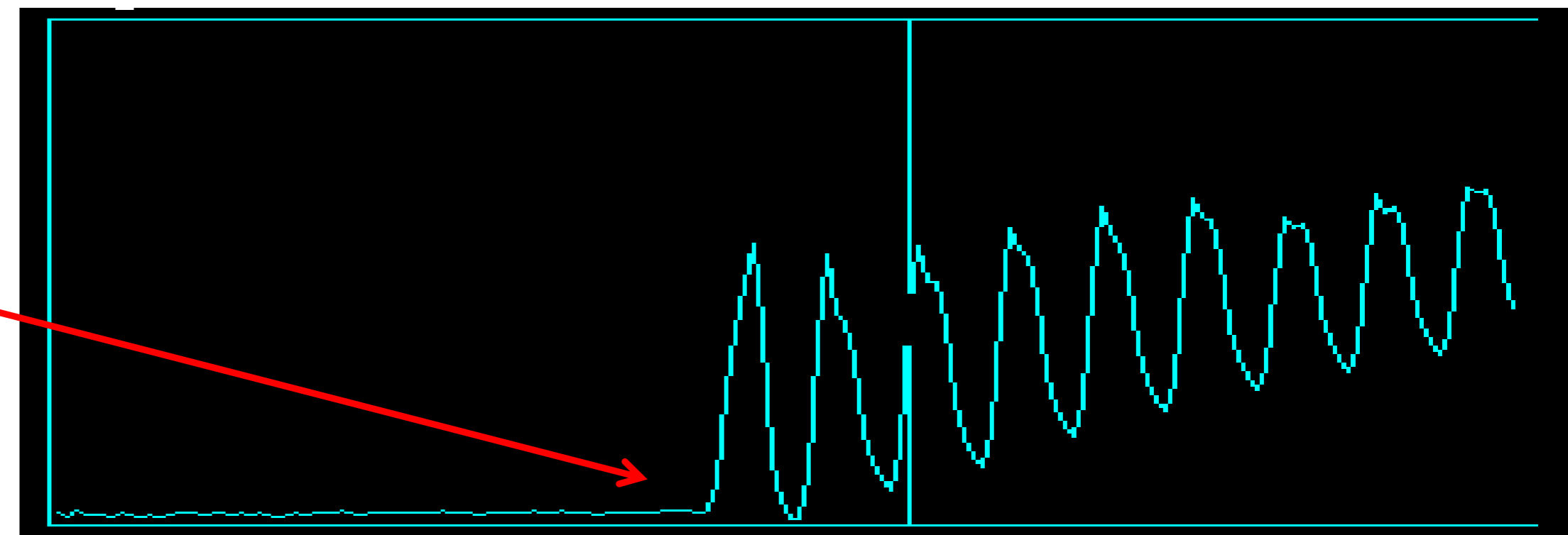
Wheel starts rolling up on part here

Displacement



Current

Current starting before wheel comes in contact with part overheats front edge of part

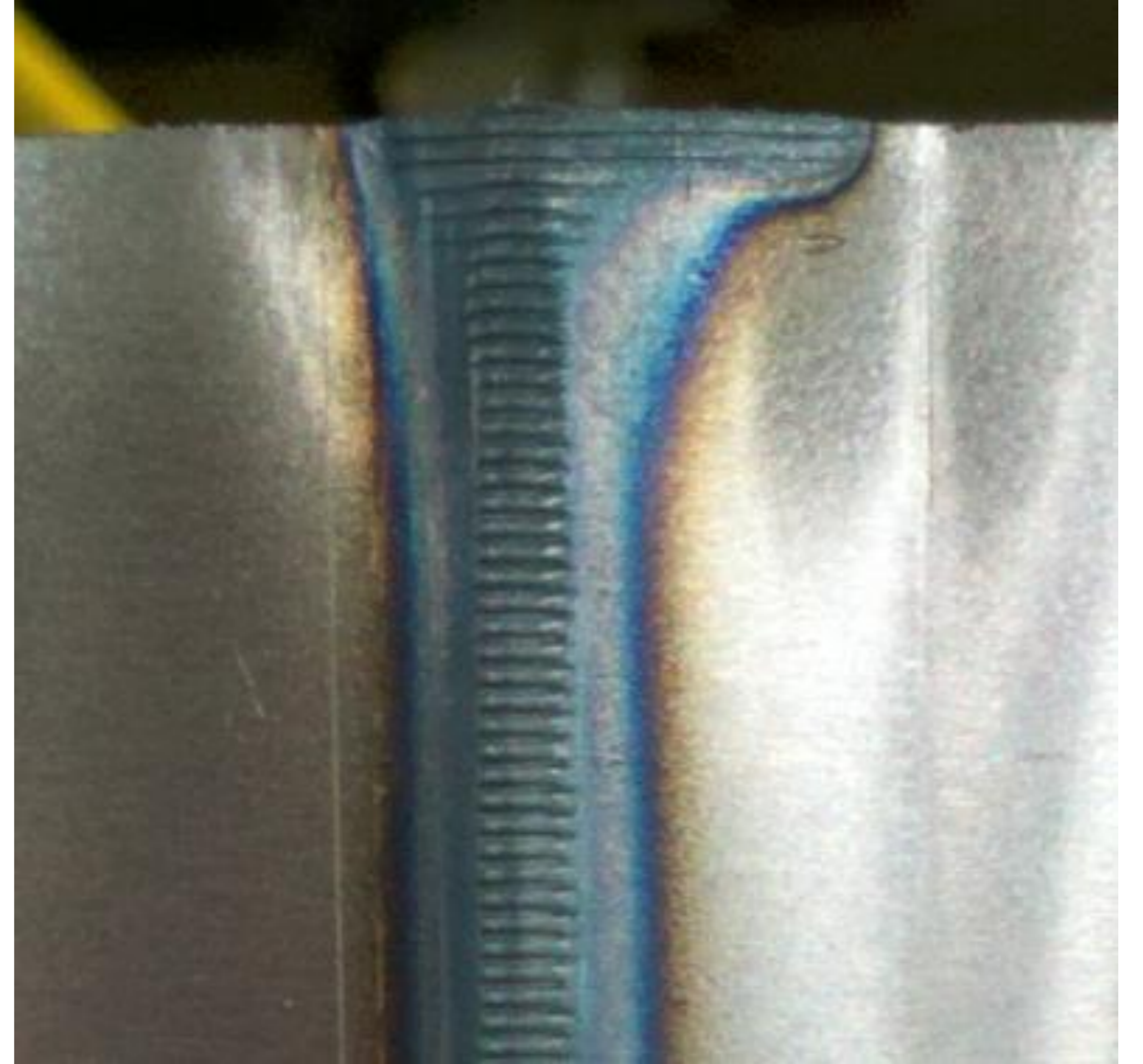


Data collected with WeldView® Monitor

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**Poorly Regulated Heat Pulses,  
with Uncontrolled Heat  
Envelope, Turning on Too Soon  
Overheats Front of Part**





# What does it take to reliably weld parts like this?

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- Use control that delivers accurate repeatable heat
- Employ adaptive control to:
  - Profile heat envelope rolling up on part
  - Compensate for bounce of wheel landing on part
  - Adjust heat for overlap & wheel contact area variations on part.
  - Compensate for velocity fluctuations
  - Profile heat envelope rolling off back of part
  - Instantly cut off heat rolling off back edge of part



# Water Heater Front Edge Adaptive Weld

**Non Adaptive – Poor heat control results in too much heat too soon**



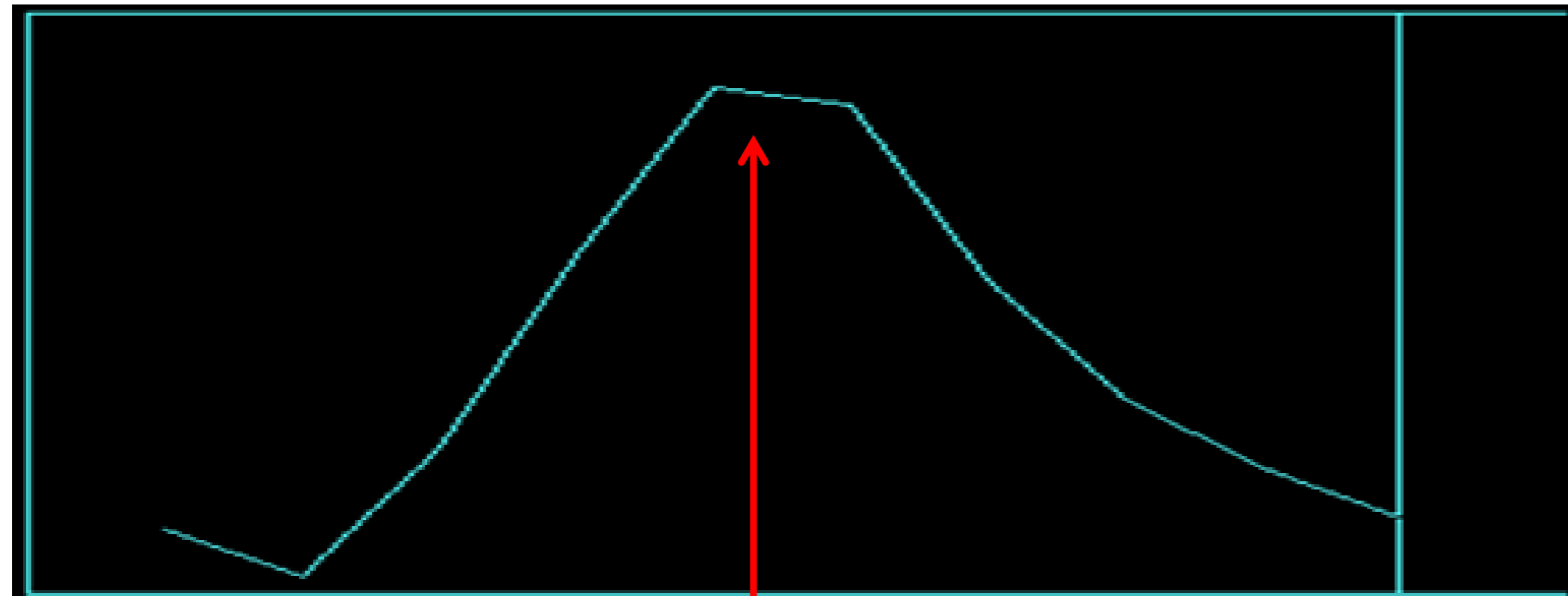
**Adaptive - Heat envelop is precisely coordinated with front edge of part**





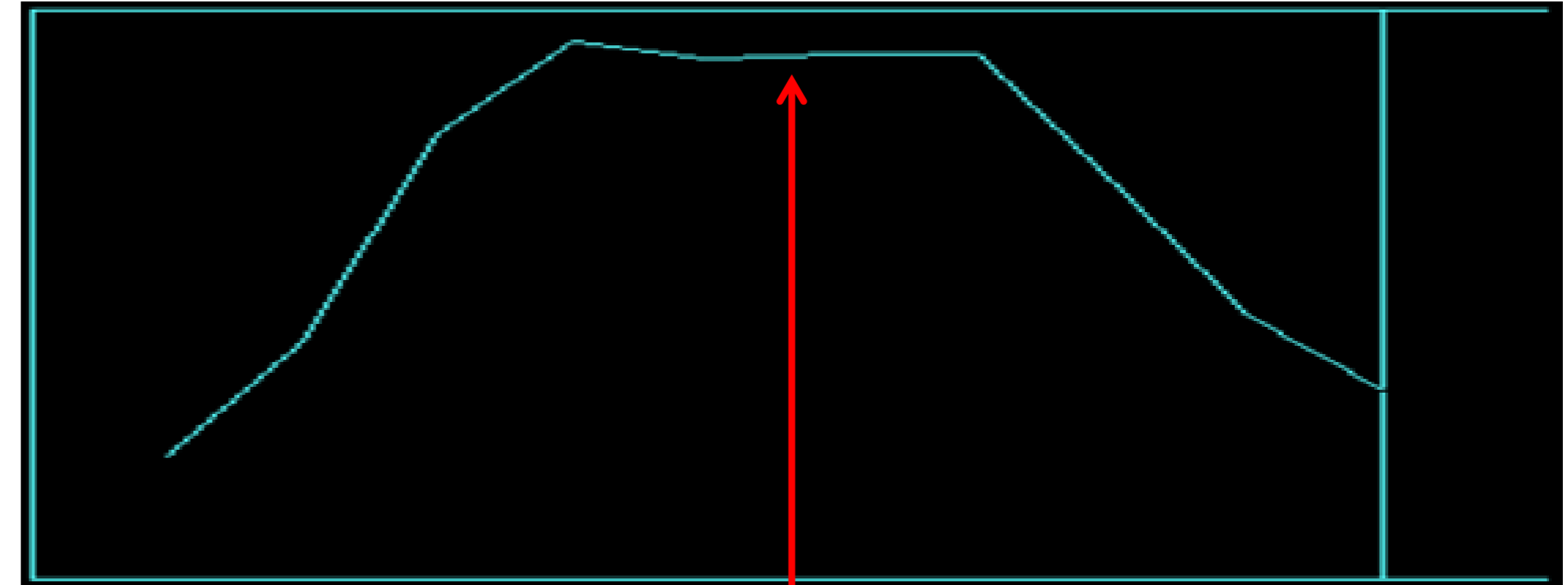
# 170th Weld Impulse on 55 Gallon Drum Produced with 386 Weld Current Impulses

Both of these pulses should look identical



Current pulse too narrow creates leak from undersized weld

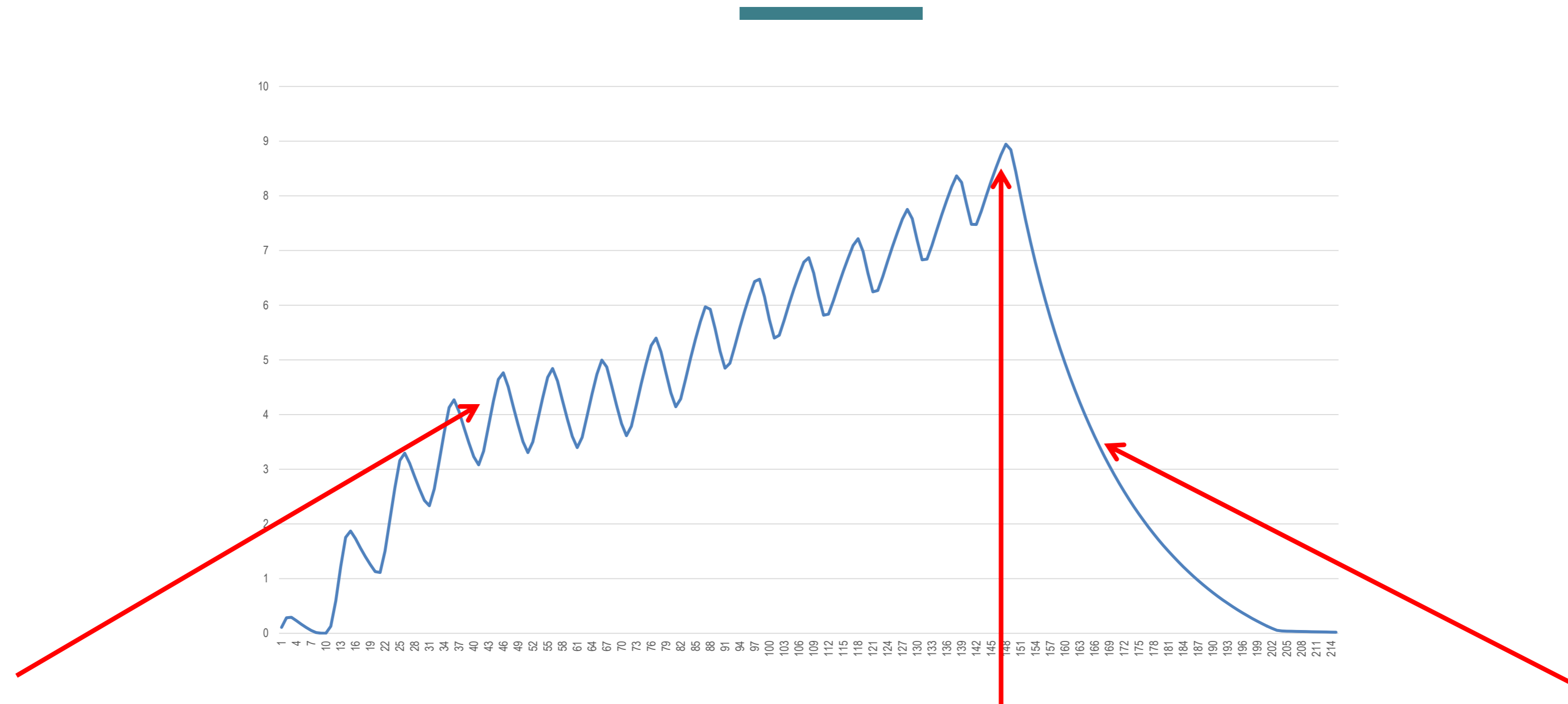
Instead there is more than 80% variation in peak current duration



Current pulse too wide creates leak from expelled material

Current trace of seam with 386 current impulses recorded with WeldView® Monitor

# MFDC Can Have Big Current Fluctuations and Excessive Decay Time



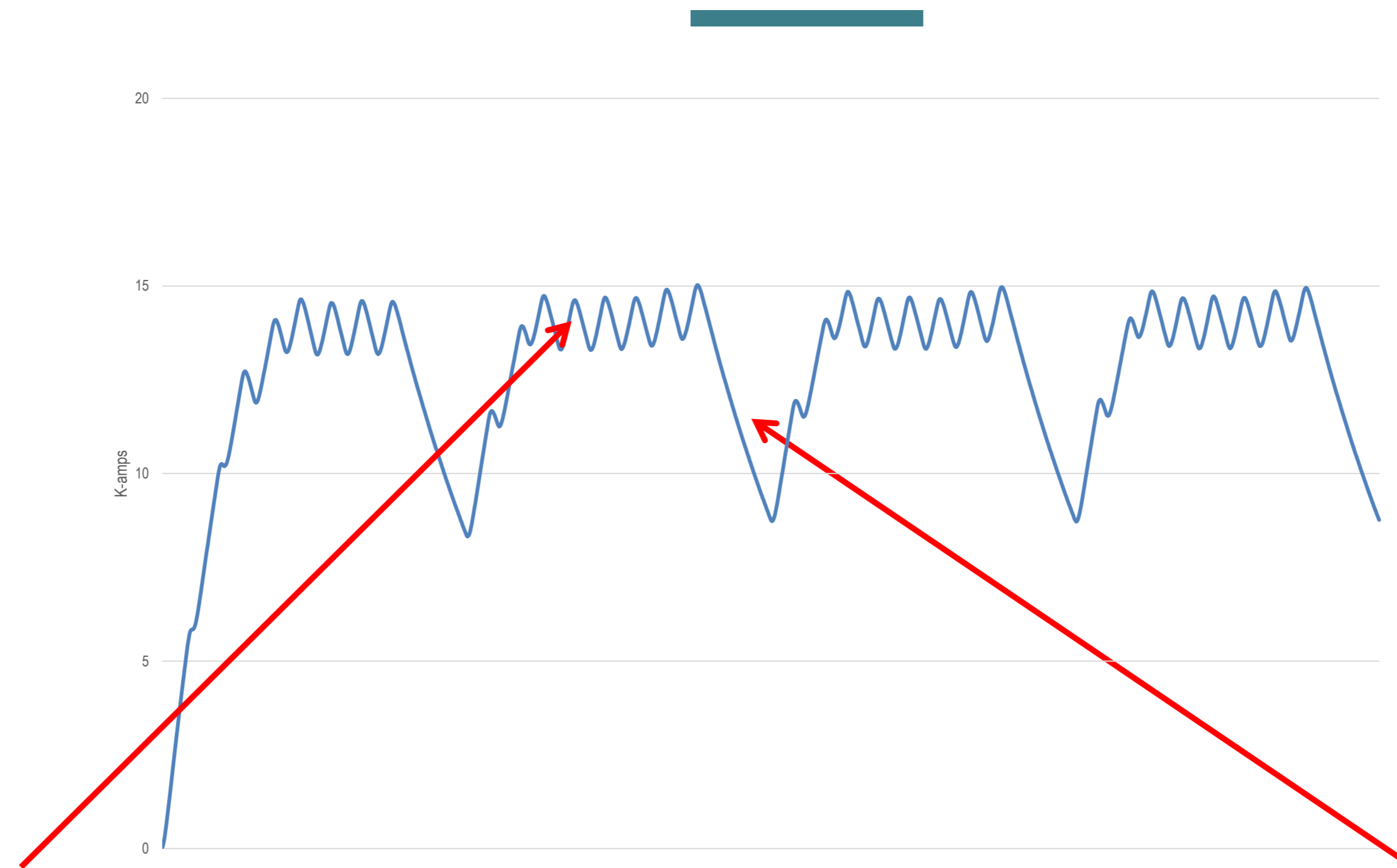
Big current fluctuations reduces stability of process

Current still rising at end of programmed heat means process is uncontrolled

Long current decay during cool time means hotter wheels

**Current trace recorded with WeldView® Monitor**

# MFDC weld impulses with 4 ms heat 1ms cool has ineffective cooling



Big current fluctuations caused by MFDC reduces stability of process

Long current decay during cool time means hotter wheels

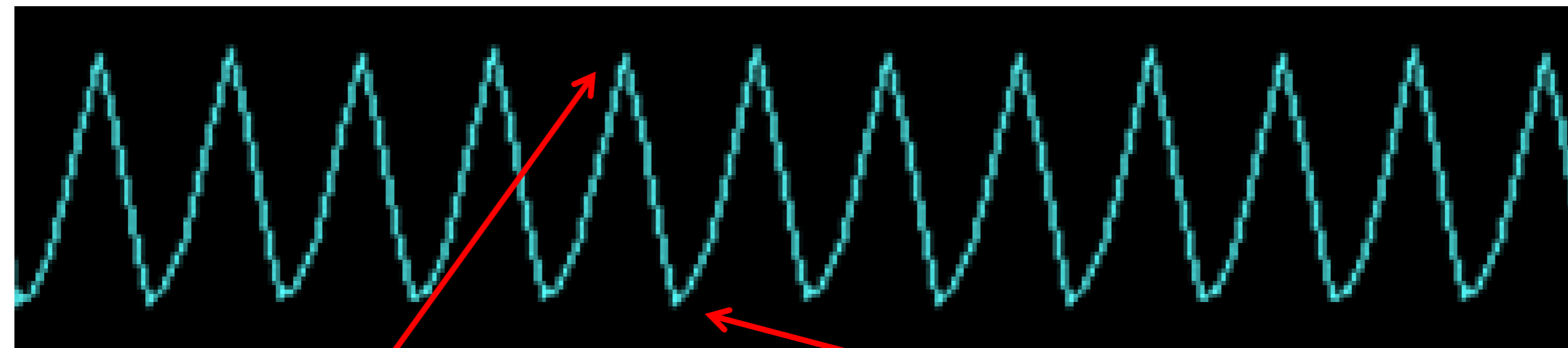
**Current trace recorded with WeldView® Monitor**



# MFDC Control Programmed to Produce 15.1ka for 5ms Followed by 3ms Cool Time in a Repeating Pattern

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- Process is unregulated when control never reaches programmed current targets
- Seam performance is compromised when high currents persist during cool times



Current overshoots to 18kA  
by end of 5ms of applied heat

Current only decays to 13.5kA at  
end of programmed cool time

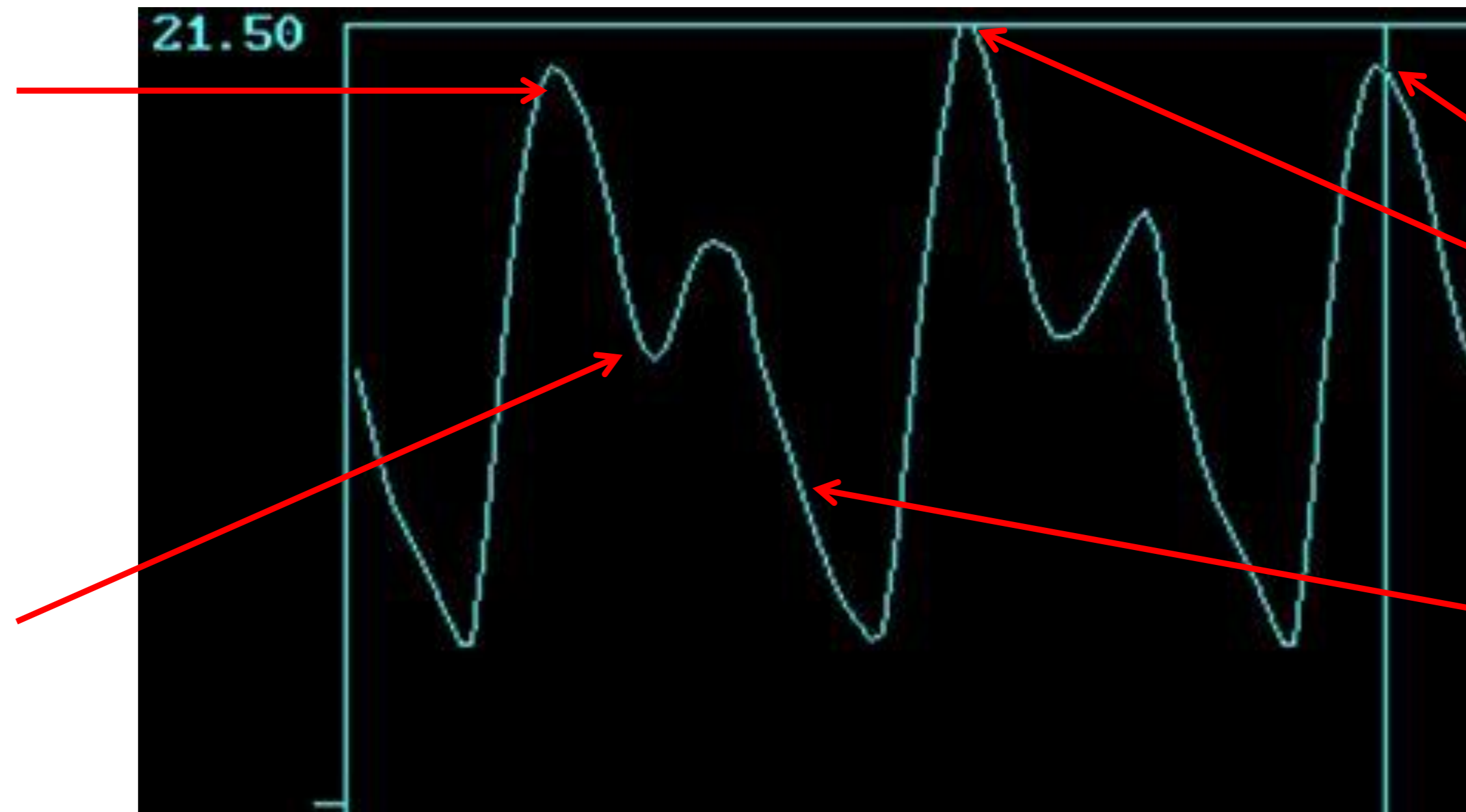
**Current trace recorded with WeldView® Monitor**

# MFDC control programmed to produce 13kA for 24ms followed by 12ms cool time in a repeating pattern

Process is unregulated when unstable current overshoots, has oscillations, and never reaches programmed current targets

Current overshoot followed by current undershoot represents 73% current fluctuation during each weld

Undershoot occurring 8 ms after overshoot



Peak current fluctuates 15% from one impulse to the next

Current never decays to zero during cool time between impulses

Current trace recorded with WeldView® Monitor

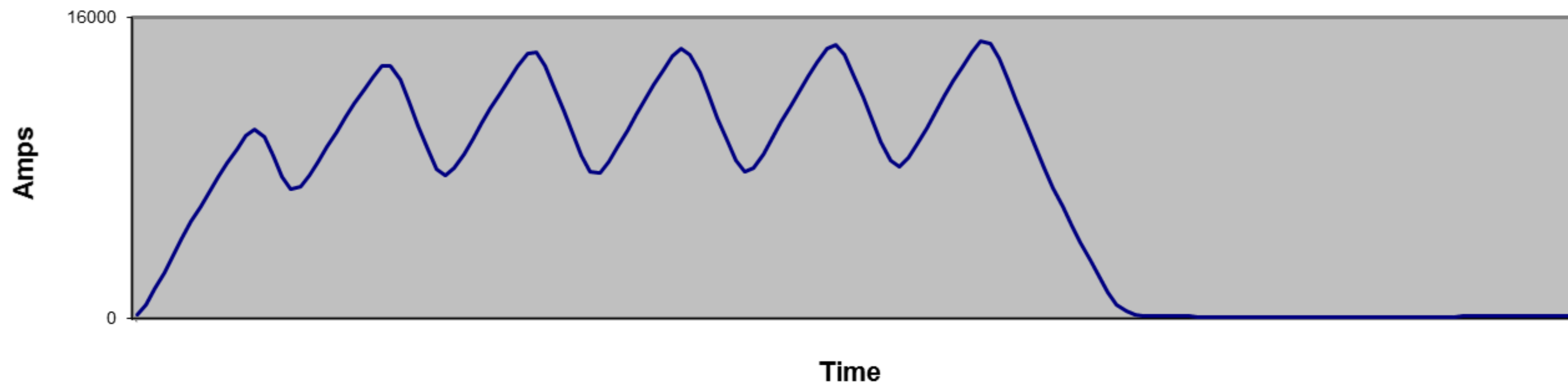
# Problems with MFDC

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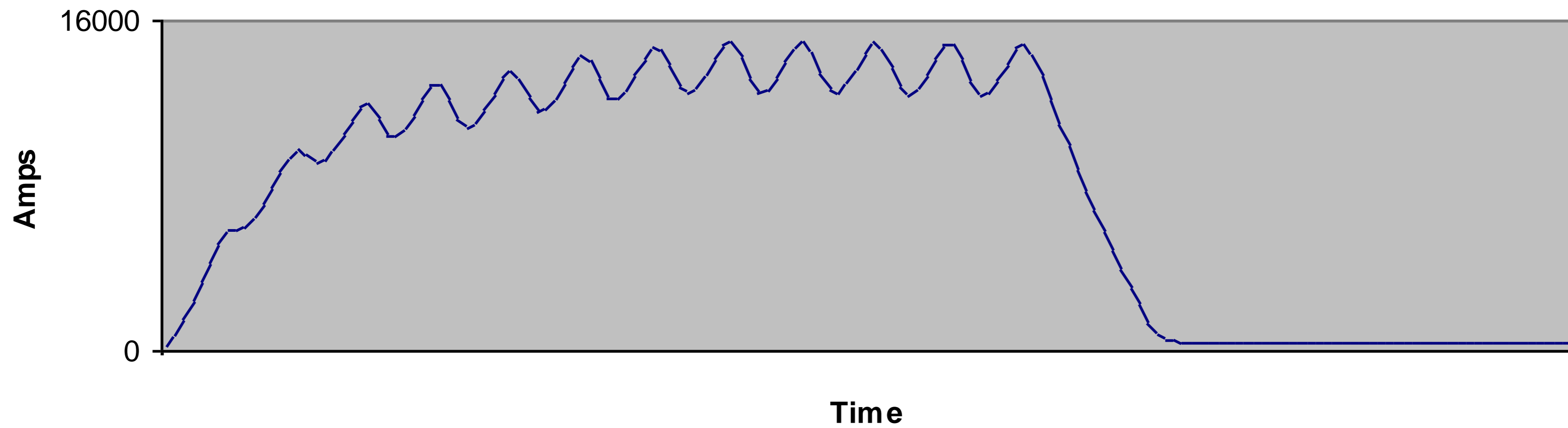
- Big mechanical disturbance from current fluctuations occurs twice per millisecond of applied heat
- Current decay time after each weld diminishes effectiveness of cool time & causes wheels to run hotter
- Magnetizes machine and part
- Causes heat imbalance from Peltier Effect
- Asymmetrical electrode wear
- Limited current adjustment rate



**3 ms Weld Produced with 6 Pulses at a 2kHz Switching Frequency**

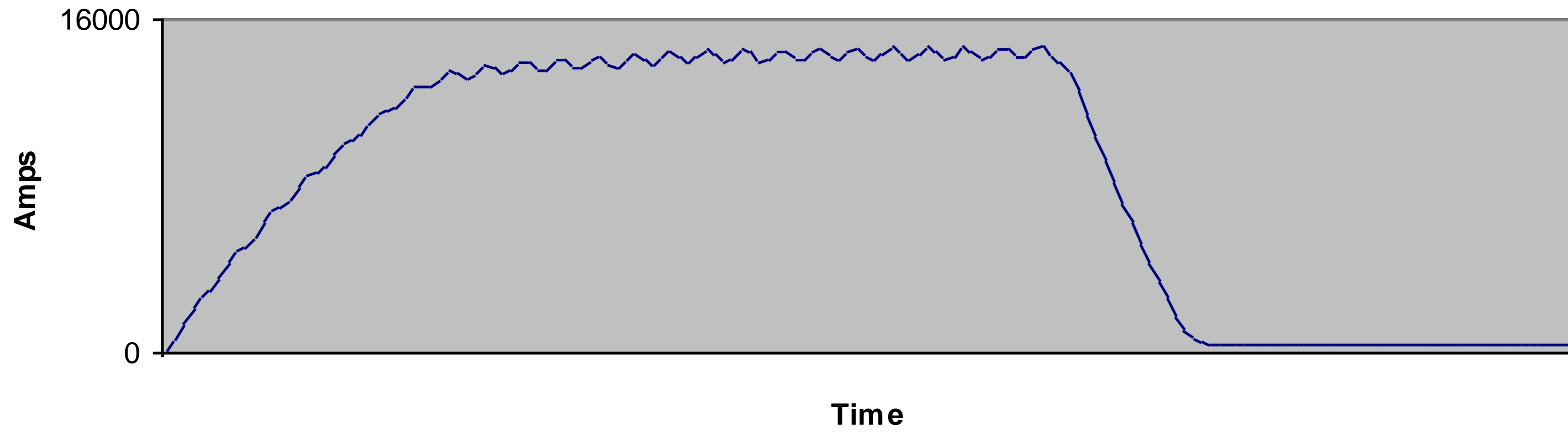


**3 ms Weld Produced with 12 Pulses at 4kHz Switching Frequency**

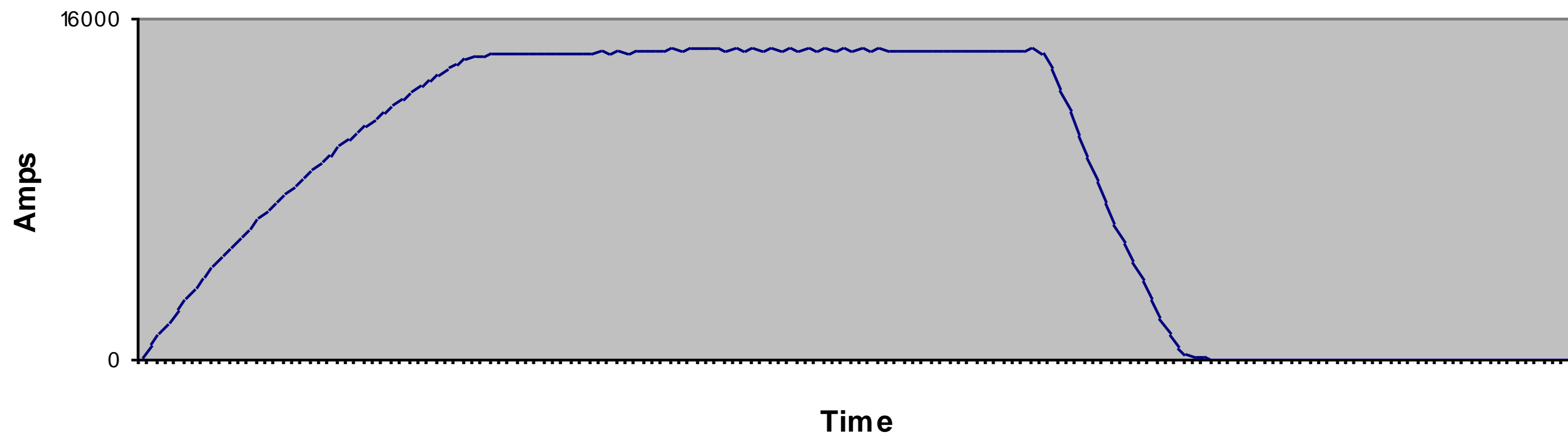




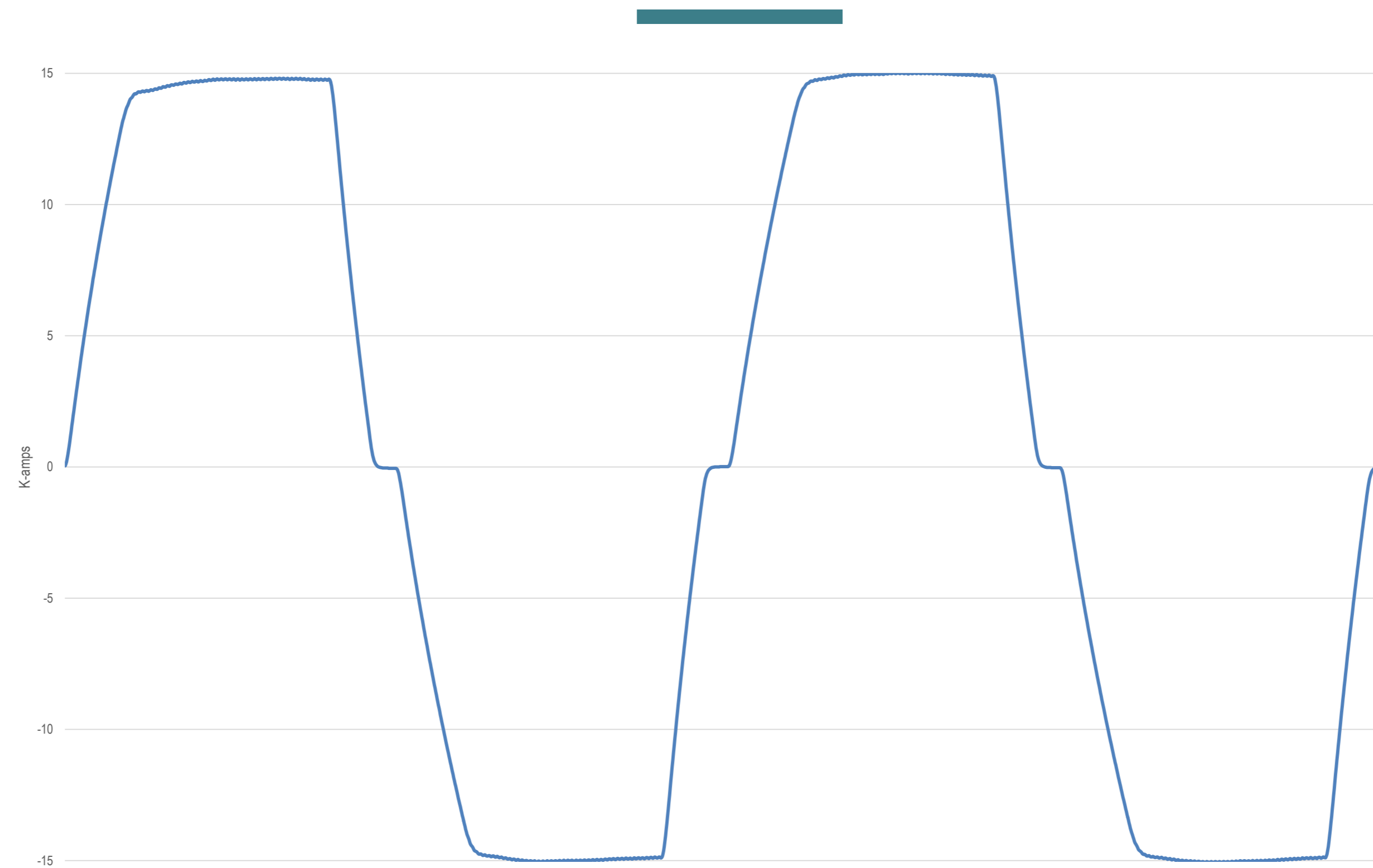
**3 ms Weld Produced with 24 Pulses at 8kHz Switching Frequency**



**3 ms Weld Produced with 48 Pulses at 16kHz Switching Frequency**

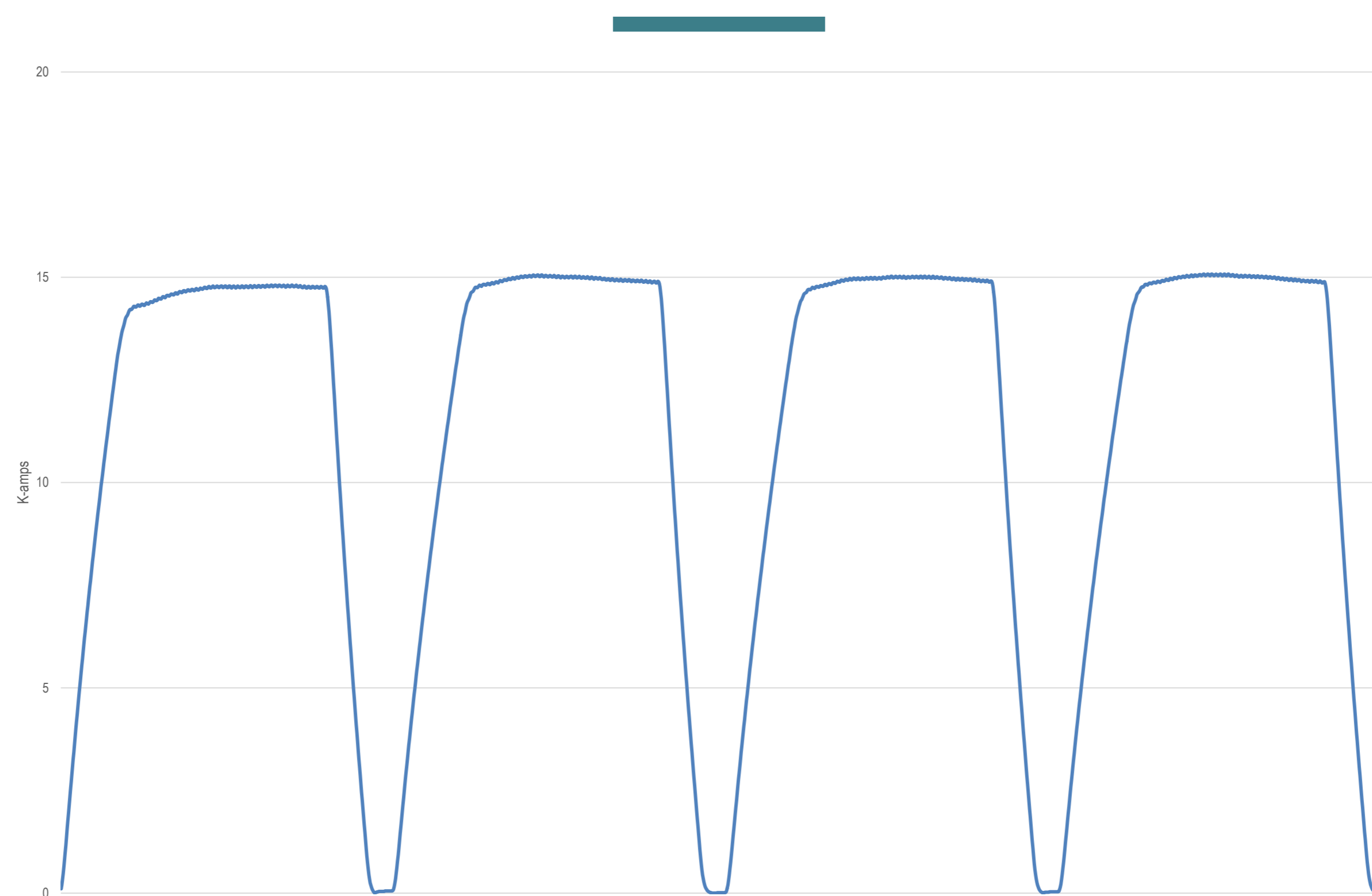


# Instantaneous current waveform of 4 ms heat 1ms cool weld impulses produced with WeldComputer® Wave Synthesis Control and 60 Hz AC transformer



**Current trace recorded with WeldView® Monitor**

# RMS current trace of 4 ms heat 1ms cool weld impulses produced with WeldComputer® Wave Synthesis Control and 60 Hz AC transformer



**Current trace recorded with WeldView® Monitor**

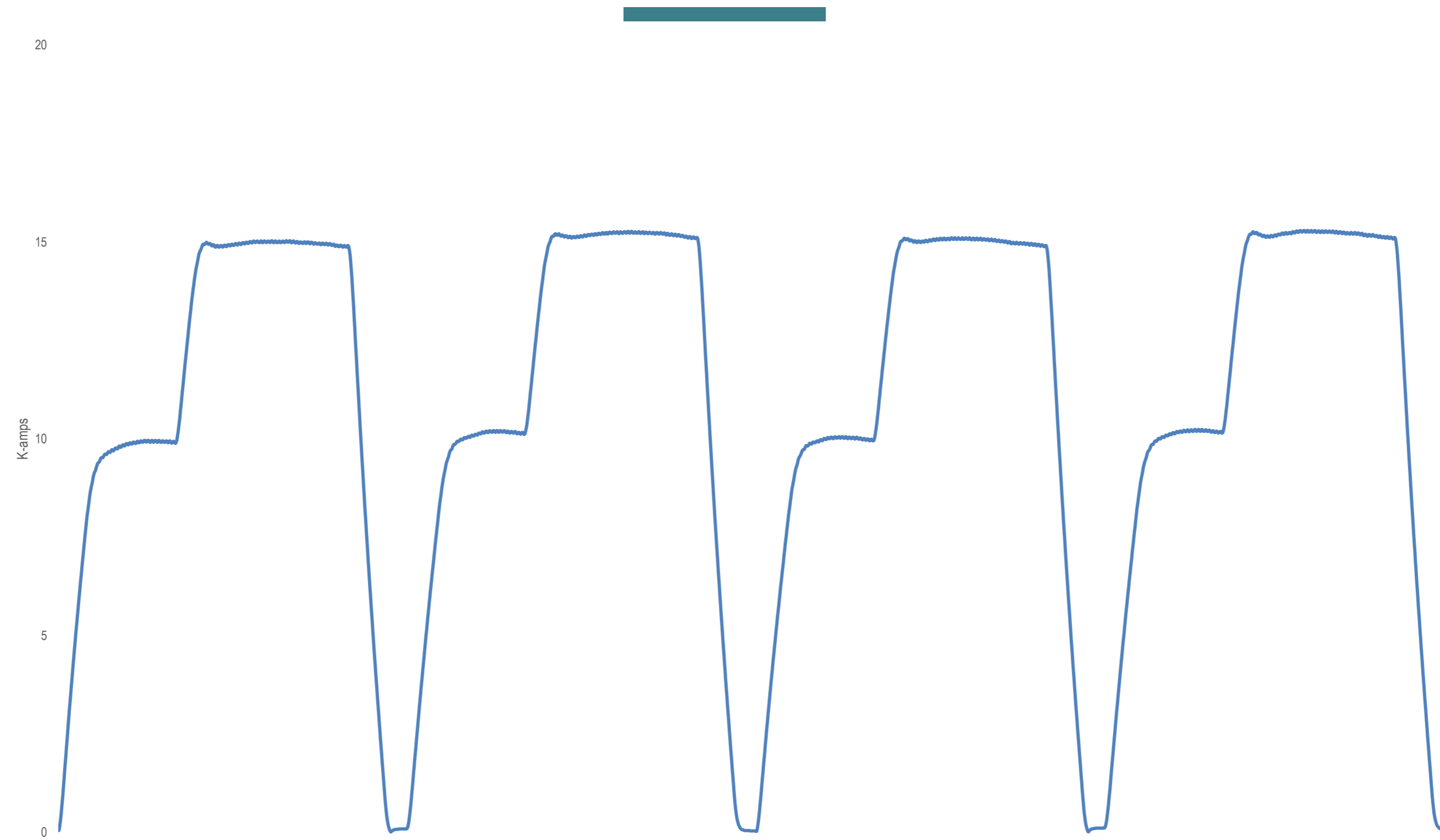


# Instantaneous current waveform of 2 ms preheat, 3 ms weld heat, 1ms cool weld impulses produced with WeldComputer® Wave Synthesis Control and 60 Hz AC transformer



**Current trace recorded with WeldView® Monitor**

# RMS current trace of 2 ms preheat, 3 ms weld heat, 1ms cool weld impulses produced with WeldComputer® Wave Synthesis Control and 60 Hz AC transformer



**Current trace recorded with WeldView® Monitor**



60 Hz AC fixture type transformer used to produce 200 welds per second





# 2 ms preheat, 3 ms weld heat, 1ms cool weld impulses produced with WeldComputer® Wave Synthesis Control and 60 Hz AC transformer



Current trace recorded with WeldView® Monitor



# Machine Stability

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- Velocity fluctuations: can be compensated for with adaptive control
- Force fluctuations: can be compensated for with adaptive control

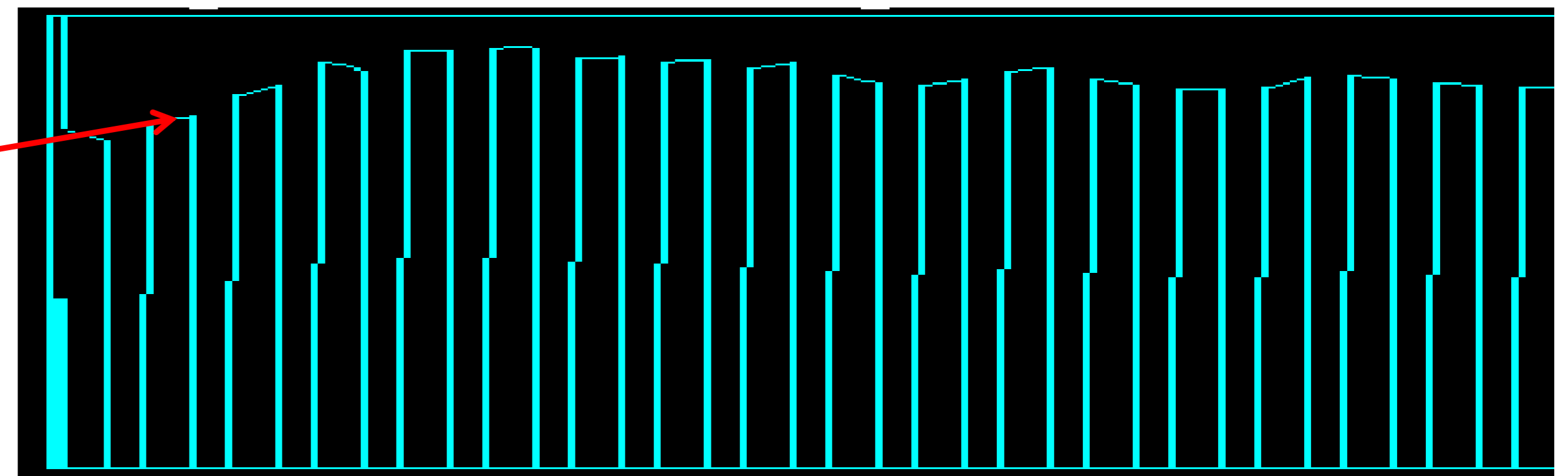
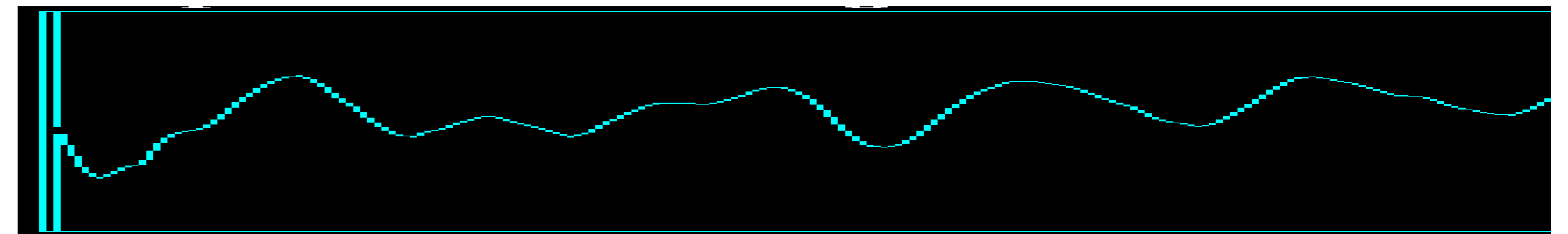
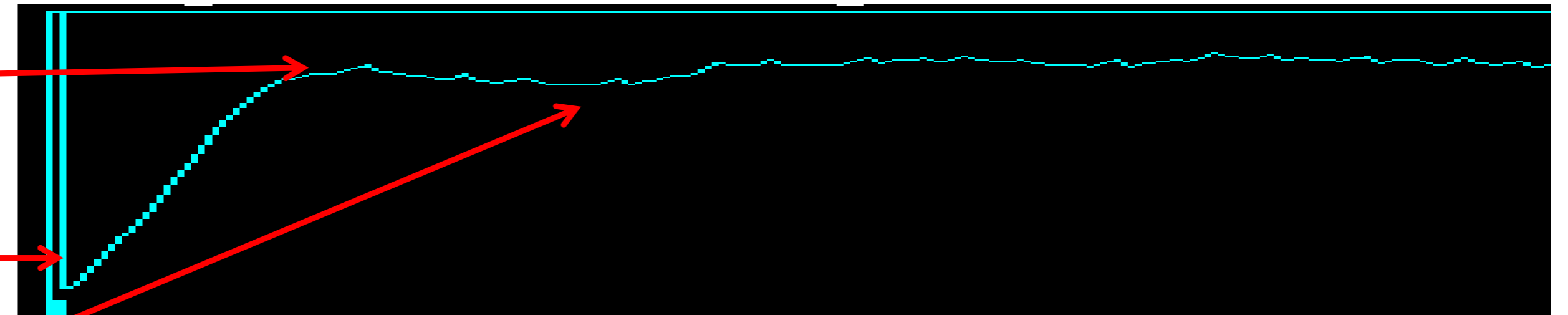
# Adaptive Seam Welding at 22.5 in/sec - Front End of Part

Wheel overshoots rolling up on front of part

Displacement of wheel rolling up on front of part triggers current

Wheel bounces when it lands on top of part

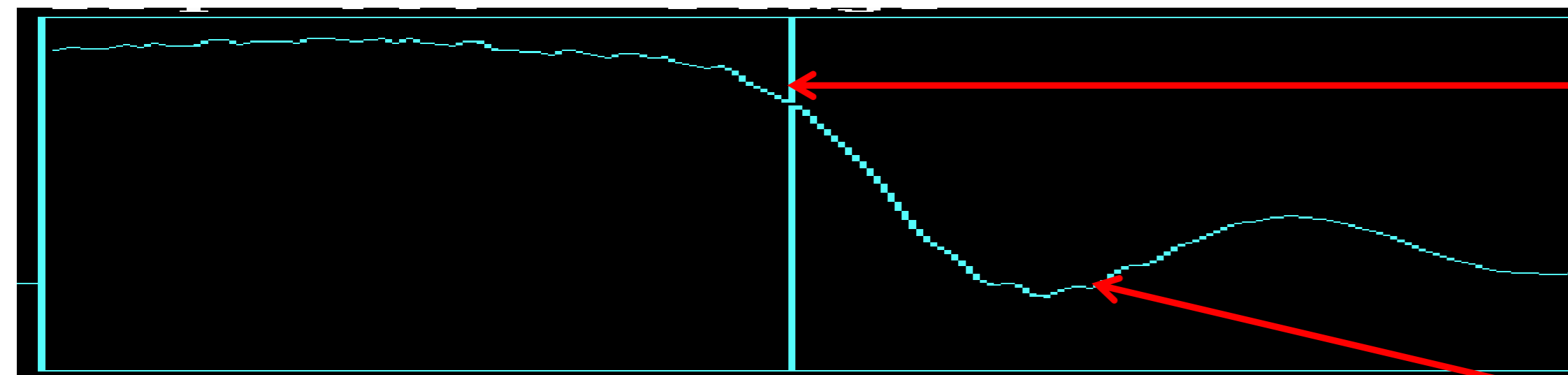
Each 5ms duration weld current pulse (below) is adjusted each 1ms to control weld based on displacement, velocity & force



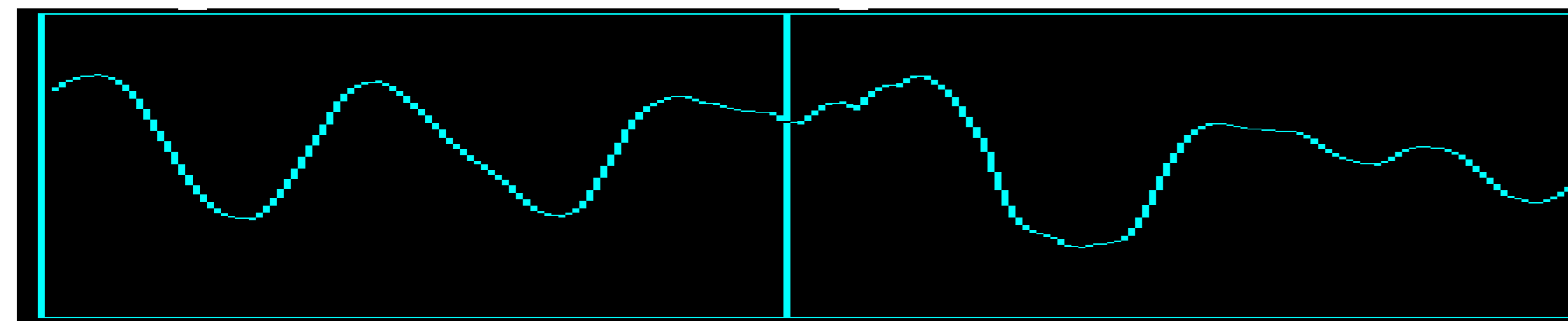
Data collected and current synthesized with WeldComputer® Adaptive Control



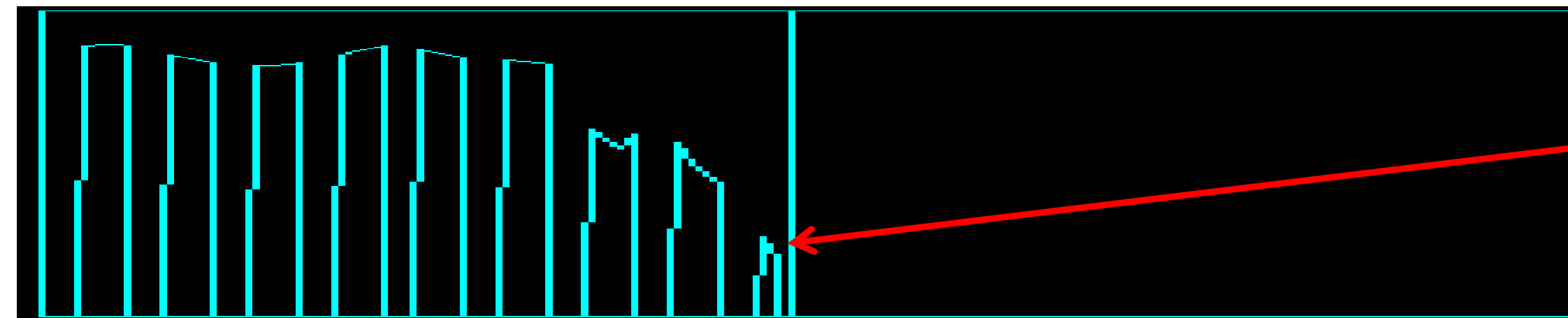
# Adaptive Seam Welding at 22.5 in/sec Back End of Part



Wheel starts rolling off back of part



Wheels bounce against each other after rolling off back of part



Heat automatically reduces itself and shuts off as wheel rolls off part

Data collected and current synthesized with WeldComputer® Adaptive Control

# Continuous Welding Speed Limiting Factors:

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- Current
- Force
- Wheel/Electrode Cooling



Reach out today to speak with one of our seam welding experts.



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